

# BOOTSTRAP METHOD IN THE BFSS MODEL

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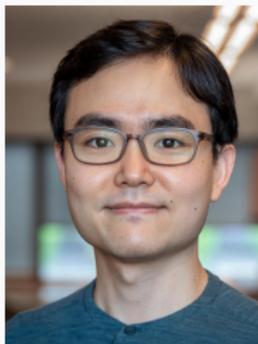


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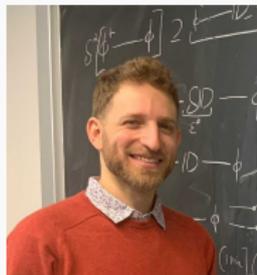
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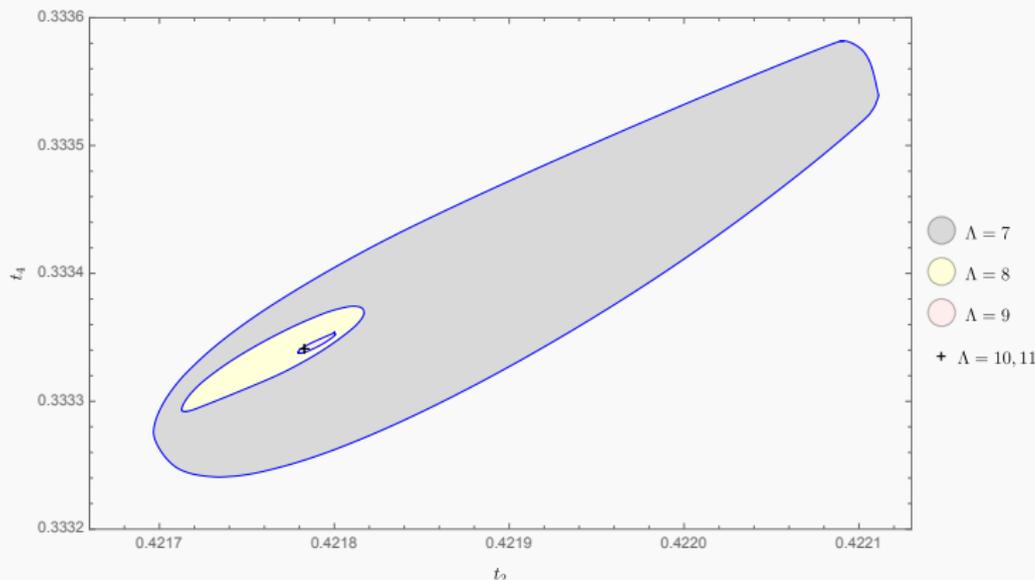


Jessica

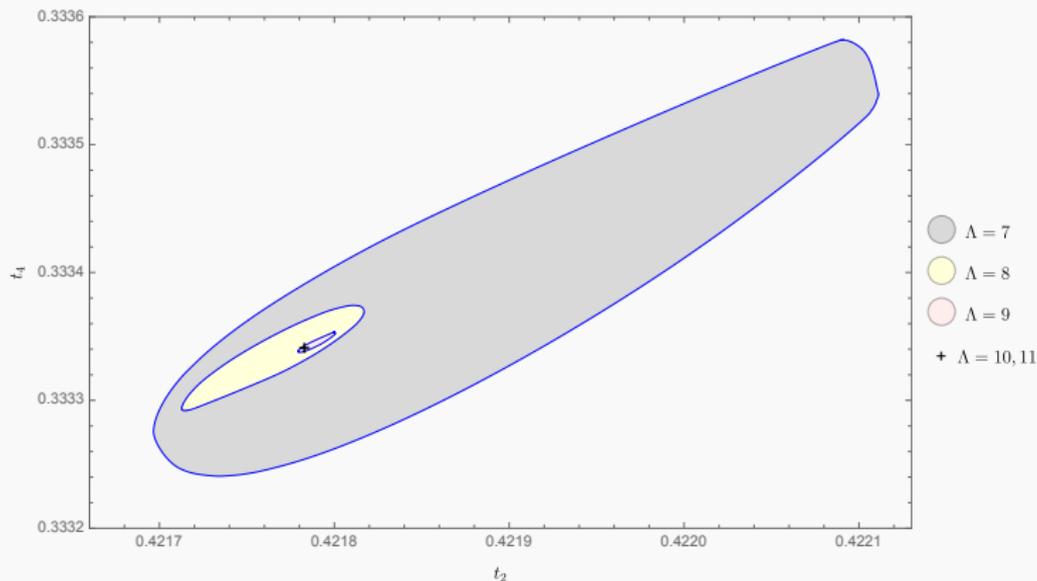
- Pioneering work on matrix quantum mechanics bootstrap [Han et al., 2020].
- Pioneering BFSS bootstrap [Lin, 2023]
- See also  
[Anderson and Kruczenski, 2017][Lin, 2020][Kazakov and Zheng, 2022]  
[Kazakov and Zheng, 2023][Kazakov and Zheng, 2024]  
[Cho et al., 2024]

# MULTI-MATRIX BOOTSTRAP [KAZAKOV AND ZHENG, 2022]

$$Z = \lim_{N \rightarrow \infty} \int d^{N^2} A d^{N^2} B e^{-N \text{tr}(-h[A,B]^2/2 + A^2/2 + gA^4/4 + B^2/2 + gB^4/4)} \quad (1)$$



# MULTI-MATRIX BOOTSTRAP [KAZAKOV AND ZHENG, 2022]



$$\Lambda = 11, g = h = 1 : \begin{cases} 0.421783612 \leq \langle \text{Tr} A^2 \rangle \leq 0.421784687 \\ 0.333341358 \leq \langle \text{Tr} A^4 \rangle \leq 0.333342131 \end{cases} \quad (3)$$

# SMALL PIECES OF OPTIMIZATION THEORY

Basically bootstrap method is solving problems in theoretical physics by optimization theory.

- Quadratic programming:

$$\begin{array}{ll} \min & y \\ \text{s.t.} & y = x^2 + 3x + 1 \end{array} \quad (4)$$

- Linear programming:

$$\begin{array}{ll} \max & 300x + 100y \\ \text{s.t.} & 6x + 3y \leq 40 \\ & x - 3y \leq 0 \\ & x + \frac{1}{4}y \leq 4 \end{array} \quad (5)$$

# SEMI-DEFINITE PROGRAMMING

- Semi-definite Programming:

$$\begin{array}{ll} \min & 2x + 3y \\ \text{s.t.} & \begin{pmatrix} x & 1 \\ 1 & y \end{pmatrix} \succeq 0 \end{array} \quad (6)$$

- Linear programming and Quadratic programming are special situations of Semi-definite Programming(SDP).
- They all fall into the class of Convex Optimization.
- Generally we cannot solve large-scale non-convex optimization problems.

MC:

- physics simplifies at large  $N$  but the computation gets harder
- sign problem, finite volume truncation, finite  $N$  truncation

# WHY BOOTSTRAP

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- no sign problem, no finite volume or finite  $N$  truncation 😊

The Hamiltonian is chosen to be [Banks, Fischler, Shenker, Susskind 97]:

$$H = \frac{1}{2} \text{Tr} \left( g^2 P_i^2 - \frac{1}{2g^2} [X_I, X_J]^2 - \psi_\alpha \gamma'_{\alpha\beta} [X_I, \psi_\beta] \right) \quad (7)$$

Here:

$$[X_{ij}, P_{kl}] = i\delta_{il}\delta_{jk}, \quad \{\psi_{\alpha,ij}, \psi_{\beta,kl}\} = \delta_{\alpha\beta}\delta_{il}\delta_{kj} \quad (8)$$

Dual to the dynamics of the D0-brane.

The matrices are in multiples of the  $SO(9)$  symmetry, with the supercharge:

$$Q_\alpha = g \text{tr} P_I \gamma'_{\alpha\beta} \psi_\beta - \frac{i}{2g} \text{tr} [X^I, X^J] \gamma''_{\alpha\beta} \psi_\beta \quad (9)$$

The goal of this work is to bootstrap the ground state of this model.

The Hamiltonian is chosen to be ( $g = 1$ ):

$$H = \frac{1}{2}(p_x^2 + p_y^2) + \frac{1}{2}gx^2y^2 \quad (10)$$

This model is not trivially solved by numerical method/analytical method [Hoppe, 1980] [Simon, 1983] [Komatsu et al., 2024]. It keeps certain key feature of the BFSS Hamiltonian:

$$H = \frac{1}{2} \text{Tr} \left( g^2 p_i^2 - \frac{1}{2g^2} [X_i, X_j]^2 - \psi_\alpha \gamma_{\alpha\beta}^I [X_i, \psi_\beta] \right) \quad (11)$$

# EQUATIONS OF MOTION

Our goal is to solve all the eigenvalues and all the expectations of the operators under different eigenstates.

For an eigenstate with eigenvalue  $E$ , the corresponding loop equations are:

$$\langle [H, \mathcal{O}] \rangle = 0, \forall \mathcal{O} \quad (12)$$

$$\langle H\mathcal{O} \rangle = E\langle \mathcal{O} \rangle, \forall \mathcal{O} \quad (13)$$

together with the Ward identities:

$$\langle \mathcal{O}_g \rangle = \langle \mathcal{O} \rangle, \forall \mathcal{O} \quad (14)$$

These are all linear equations, we can expand any operators as:

$$\mathcal{O} = \sum \alpha_{mnts} p_x^m p_y^n x^t y^s \quad (15)$$

# EQUATIONS OF MOTION

Here  $\pi_x = -ip_x$  and  $\pi_y = -ip_y$ :

$$\begin{aligned}\frac{1}{2} \langle x^2 y^4 \rangle - \frac{1}{2} \langle \pi_x^2 y^2 \rangle - E \langle y^2 \rangle - \frac{1}{2} \langle \pi_y^2 y^2 \rangle - 2 \langle \pi_y y \rangle - 1 &= 0 \\ \frac{1}{2} \langle x^4 y^2 \rangle - \frac{1}{2} \langle \pi_y^2 x^2 \rangle - E \langle x^2 \rangle - \frac{1}{2} \langle \pi_x^2 x^2 \rangle - 2 \langle \pi_x x \rangle - 1 &= 0 \\ \frac{1}{2} \langle \pi_y x^2 y^3 \rangle - \frac{1}{2} \langle \pi_y \pi_x^2 y \rangle - \langle \pi_y^2 \rangle - E \langle \pi_y y \rangle - \frac{1}{2} \langle \pi_y^3 y \rangle &= 0 \\ \frac{1}{2} \langle \pi_y x^3 y^2 \rangle - E \langle \pi_y x \rangle - \langle \pi_y \pi_x \rangle - \frac{1}{2} \langle \pi_y^3 x \rangle - \frac{1}{2} \langle \pi_y \pi_x^2 x \rangle &= 0 \\ \frac{1}{2} \langle \pi_x x^2 y^3 \rangle - E \langle \pi_x y \rangle - \frac{1}{2} \langle \pi_x^3 y \rangle - \langle \pi_y \pi_x \rangle - \frac{1}{2} \langle \pi_y^2 \pi_x y \rangle &= 0 \\ \frac{1}{2} \langle \pi_x x^3 y^2 \rangle - \frac{1}{2} \langle \pi_y^2 \pi_x x \rangle - \langle \pi_x^2 \rangle - E \langle \pi_x x \rangle - \frac{1}{2} \langle \pi_x^3 x \rangle &= 0 \\ - \langle \pi_x y \rangle - \langle \pi_y x \rangle - \frac{1}{2} \langle \pi_x^2 xy \rangle - \frac{1}{2} \langle \pi_y^2 xy \rangle &= 0\end{aligned}$$

# POSITIVITY BY INNER PRODUCT

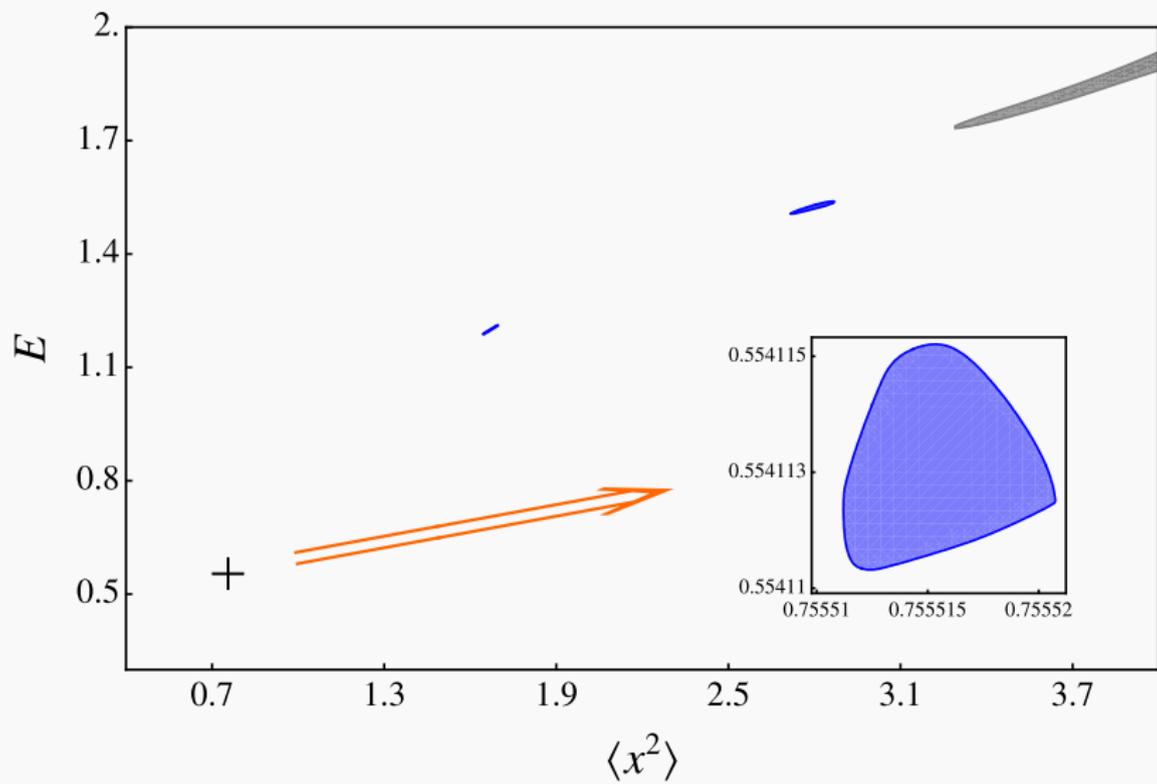
Generalization: Any inner products defined on the vector space of operators or its subspace could leads to positivity condition:

$$\langle \mathcal{O} | \mathcal{O} \rangle = \langle \mathcal{O}^\dagger \mathcal{O} \rangle = \alpha^{*\text{T}} \mathcal{M} \alpha \geq 0, \forall \alpha \Leftrightarrow \mathcal{M} \succeq 0. \quad (16)$$

Here we do the expansion  $\mathcal{O} = \sum \alpha_i \mathcal{O}_i$ ,  $\mathcal{M}_{ij} = \langle \mathcal{O}_i^\dagger \mathcal{O}_j \rangle$ .

$$\begin{matrix} & 1 & x^2 & p_x^2 & xp_x & \dots \\ 1 & \left( \begin{array}{cccccc} 1 & \langle x^2 \rangle & \langle p_x^2 \rangle & \langle xp_x \rangle & \dots \\ \langle x^2 \rangle & \langle x^4 \rangle & \langle x^2 p_x^2 \rangle & \langle x^3 p_x \rangle & \dots \\ \langle p_x^2 \rangle & \langle p_x^2 x^2 \rangle & \langle p_x^4 \rangle & \langle p_x^2 xp_x \rangle & \dots \\ \langle p_x x \rangle & \langle p_x x^3 \rangle & \langle p_x xp_x^2 \rangle & \langle p_x x^2 p_x \rangle & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{array} \right) & \succeq 0. \end{matrix}$$

# TOY MODEL( $\Lambda = 12$ )



# GROUND STATE POSITIVITY

For the ground state, or more generally, any stationary state, the corresponding positivities are:

$$\langle \mathcal{O}^\dagger \mathcal{O} \rangle \geq 0, \forall \mathcal{O} \quad (17)$$

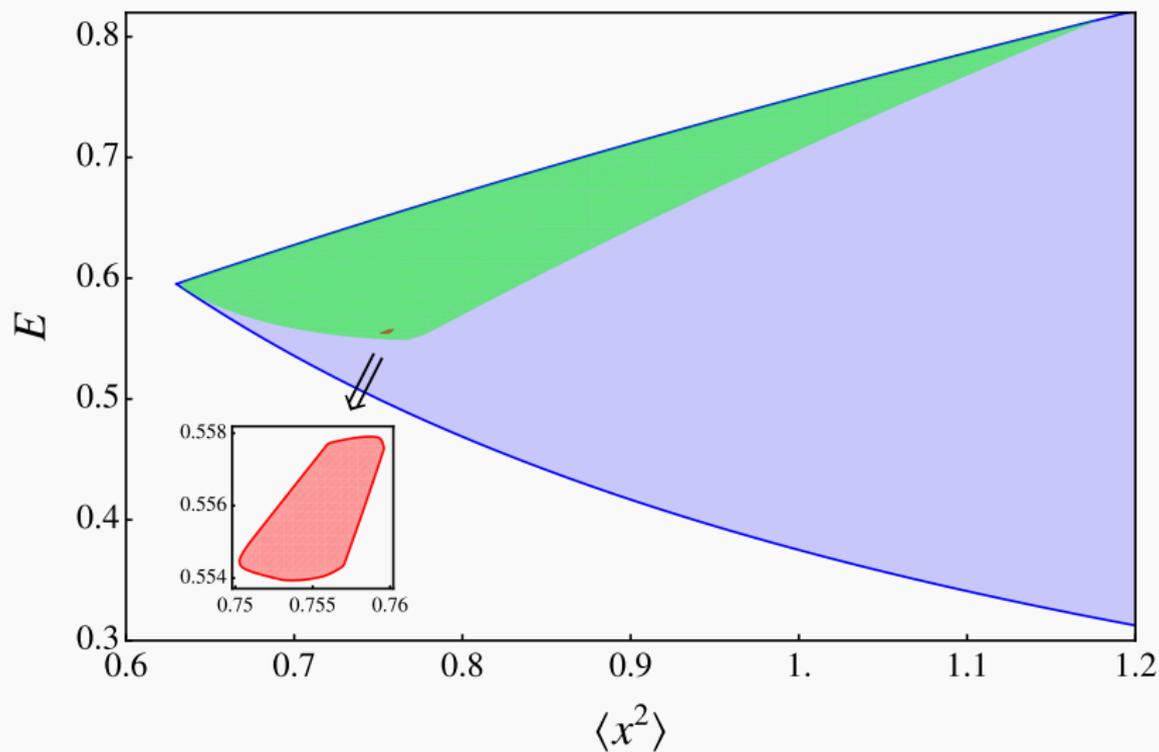
$$\langle \mathcal{O}^\dagger [H, \mathcal{O}] \rangle \geq 0, \forall \mathcal{O} \quad (18)$$

The later positivity is specialized for the ground state. For more general thermal state with inverse temperature  $\beta$  [Fawzi, Fawzi and Scalet 23][Cho et al., 2024],

$$\langle \mathcal{O}^\dagger \mathcal{O} \rangle \log \frac{\langle \mathcal{O}^\dagger \mathcal{O} \rangle}{\langle \mathcal{O} \mathcal{O}^\dagger \rangle} \leq \beta \langle \mathcal{O}^\dagger [H, \mathcal{O}] \rangle, \forall \mathcal{O} \quad (19)$$

Mathematically, these positivities together with the loop equations are necessary and sufficient.

# GROUND STATE ( $\Lambda = 4, 6, 8$ )



# GROUND STATE( $\Lambda = 10$ )

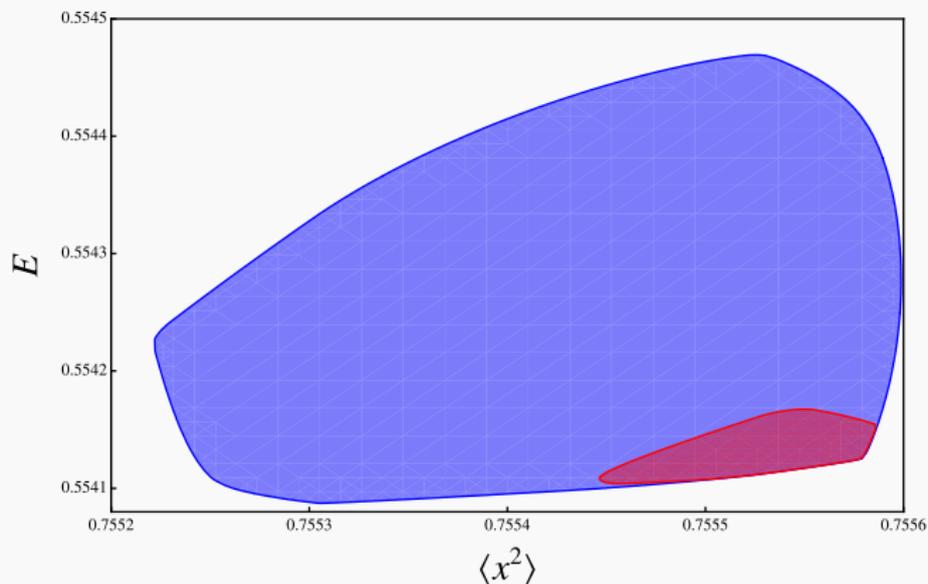


Figure 1: The bootstrap allowed region at  $\Lambda = 10$  with/without ground state positivity.

# ONE-MATRIX QUANTUM MECHANICS

The Hamiltonian is chosen to be:

$$H = \text{tr}(P^2 + X^2 + gX^4) \quad (20)$$

Here  $X$  is a large  $N$  Hermitian matrix:

$$[X_{ij}, P_{kl}] = i\delta_{il}\delta_{jk} \quad (21)$$

The ground state is known to be solvable.

# LOOP EQUATIONS

The corresponding loop equations are:

$$\langle [H, \mathcal{O}] \rangle = 0, \forall \mathcal{O} \quad (22)$$

$$\langle \text{tr}(G\mathcal{O}) \rangle = 0, \forall \mathcal{O} \quad (23)$$

together with the cyclicity of  $\text{tr}\mathcal{O}$ .  $G = i[X, P] + I$  is the generator of the  $SU(N)$  gauge symmetry.

Result: general words in  $P$  and  $X$  can be reduced to polynomials of  $\text{tr}X^m$ .

$$\begin{aligned} \langle \text{tr}P^2X^2P^2X^4 \rangle &= \frac{12}{77}g^2\langle \text{tr}X^{14} \rangle - \frac{2}{3}g\langle \text{tr}X^2 \rangle \langle \text{tr}X^6 \rangle - \frac{1}{5}g\langle \text{tr}X^8 \rangle + \frac{40}{231}g\langle \text{tr}X^{12} \rangle \\ &+ \frac{\langle \text{tr}X^2 \rangle}{24} - \frac{1}{3}\langle \text{tr}X^2 \rangle \langle \text{tr}X^4 \rangle - \frac{\langle \text{tr}X^6 \rangle}{10} + \frac{\langle \text{tr}X^{10} \rangle}{21} \end{aligned} \quad (24)$$

For the ground state, or more generally, any stationary state, the corresponding loop equations are:

$$\langle \mathcal{O}^\dagger \mathcal{O} \rangle \geq 0, \forall \mathcal{O} \quad (25)$$

$$\langle \mathcal{O}^\dagger [H, \mathcal{O}] \rangle \geq 0, \forall \mathcal{O} \quad (26)$$

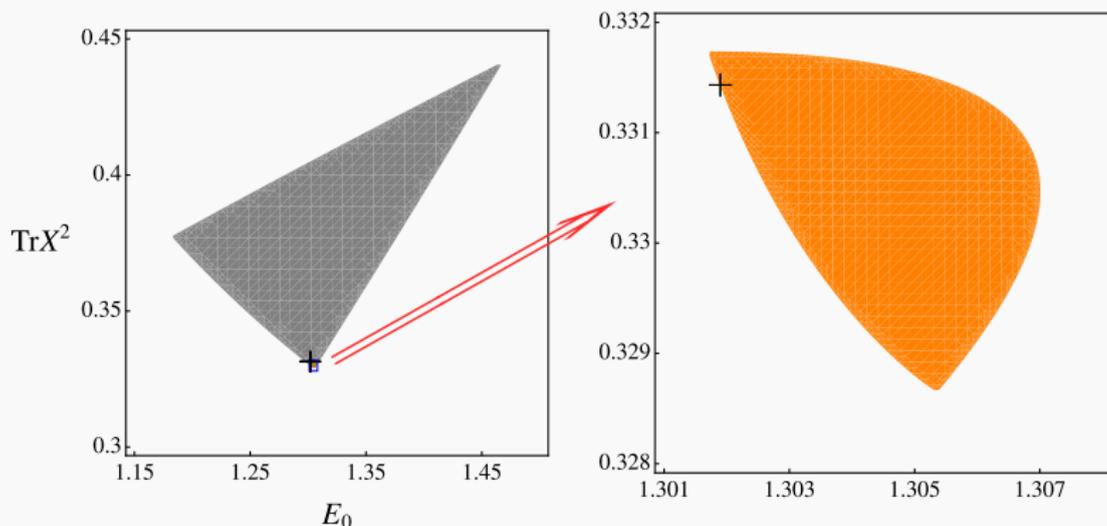
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Mathematically, these positivities together with the loop equations is necessary and sufficient.

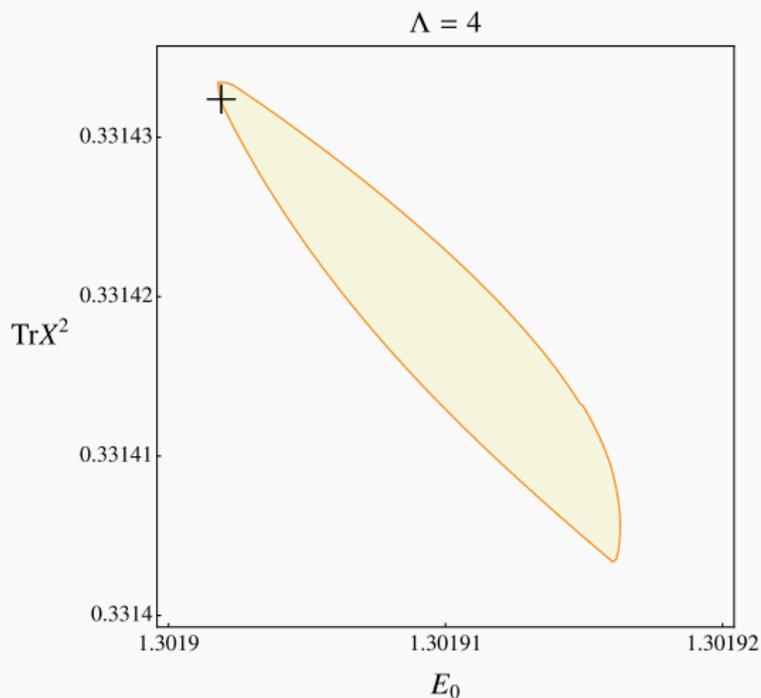
# CONVERGENCE

The illustration of convergence, the left one is  $\Lambda = 2$ , whereas the right one corresponds to  $\Lambda = 3$ . The size of the SDP matrix is 2, 2, 2 and 3, 3, 2, 3, respectively,



# CONVERGENCE

The size of the SDP matrices are 5, 4, 4, 4.



The Hamiltonian is chosen to be [Banks, Fischler, Shenker, Susskind 97]:

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Here:

$$[X_{ij}, P_{kl}] = i\delta_{il}\delta_{jk}, \quad \{\psi_{\alpha,ij}, \psi_{\beta,kl}\} = \delta_{\alpha\beta}\delta_{il}\delta_{kj} \quad (29)$$

Dual to the dynamics of the D0-brane.

The matrices are in multiples of the  $SO(9)$  symmetry, with the supercharge:

$$Q_\alpha = g \text{tr} P_I \gamma'_{\alpha\beta} \psi_\beta - \frac{i}{2g} \text{tr} [X^I, X^J] \gamma''_{\alpha\beta} \psi_\beta \quad (30)$$

Equalities:

$$\langle [H, \mathcal{O}] \rangle = 0 \quad (31)$$

$$\langle \{Q_\alpha, \mathcal{O}_\alpha\} \rangle = 0 \quad (32)$$

$$\langle \mathcal{O}_1 \mathcal{O}_2 \rangle = \langle \mathcal{O}_2 \mathcal{O}_1 \rangle - \langle [\mathcal{O}_1, \mathcal{O}_2] \rangle \quad (33)$$

$$\langle \text{tr}(C_{ij} \mathcal{O}_{ji}) \rangle = 0, \forall \mathcal{O} \quad (34)$$

This is the gauge singlet condition:

$$C_{ij} = -i[X^l, P^l]_{ij} - \psi_{ik}^\alpha \psi_{kj}^\alpha - \mathbf{1}_{ij} \quad (35)$$

Positivities:

$$\langle \mathcal{O}^\dagger \mathcal{O} \rangle \geq 0, \forall \mathcal{O} \quad (36)$$

$$\langle \mathcal{O}^\dagger [H, \mathcal{O}] \rangle \geq 0, \forall \mathcal{O} \quad (37)$$

Equalities:

$$\langle [H, \mathcal{O}] \rangle = 0 \quad (38)$$

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$$\langle \mathcal{O}_1 \mathcal{O}_2 \rangle = \langle \mathcal{O}_2 \mathcal{O}_1 \rangle - \langle [\mathcal{O}_1, \mathcal{O}_2] \rangle \quad (40)$$

$$\langle \text{tr}(C_{ij} \mathcal{O}_{ji}) \rangle = 0, \forall \mathcal{O} \quad (41)$$

This is the gauge singlet condition:

$$C_{ij} = -i[X^l, P^l]_{ij} - \psi_{ik}^\alpha \psi_{kj}^\alpha - \mathbf{1}_{ij} \quad (42)$$

Positivities:

$$\langle \mathcal{O}^\dagger \mathcal{O} \rangle \geq 0, \forall \mathcal{O} \quad (43)$$

$$\langle \mathcal{O}^\dagger [H, \mathcal{O}] \rangle \geq 0, \forall \mathcal{O} \quad (44)$$

Variables:

$$\langle \text{tr} \mathcal{O} \rangle, \quad \mathcal{O} = \mathcal{O}_{ind} \mathcal{I}^{ind}, \quad (45)$$

e.g.  $\langle \text{tr} \psi_{\alpha_1} \psi_{\alpha_2} \psi_{\alpha_3} \psi_{\alpha_4} \rangle \gamma_{\alpha_1 \alpha_2}^l \gamma_{\alpha_3 \alpha_4}^l, \quad \langle \text{tr} X^{l_1} \dots X^{l_9} \rangle \epsilon^{l_1 l_2 \dots l_9}$

The algebra of SO(9) invariant tensors can be generated from:

$$\delta^{IJ}, \quad \epsilon^{l_1 l_2 \dots l_9}, \quad \gamma_{\alpha\beta}^l. \quad (46)$$

A linear basis of invariant tensors is a non-trivial task.

$$\delta_{\alpha\eta} \delta_{\beta\epsilon} = \frac{1}{16} \gamma_{\alpha\beta}^l \gamma_{\eta\epsilon}^l + \frac{1}{16} \delta_{\alpha\beta} \delta_{\eta\epsilon} + \frac{1}{32} \gamma_{\alpha\beta}^{IJ} \gamma_{\eta\epsilon}^{IJ} + \frac{1}{96} \gamma_{\alpha\beta}^{IJK} \gamma_{\eta\epsilon}^{IJK} + \frac{1}{384} \gamma_{\alpha\beta}^{IJKL} \gamma_{\eta\epsilon}^{IJKL} \quad (47)$$

Equations:

$$0 = \gamma_{\beta\alpha}^I \langle \text{tr} P^I \psi_\beta \psi_\alpha \rangle + \gamma_{\beta\alpha}^I \langle \text{tr} \psi_\beta P^I \psi_\alpha \rangle$$

$$0 = -\gamma_{\beta\alpha}^I \langle \text{tr} \psi_\beta X^I \psi_\alpha \rangle - \gamma_{\beta\alpha}^I \langle \text{tr} \psi_\beta \psi_\alpha X^I \rangle$$

$$0 = -16 \langle \text{tr} P^I P^I \rangle - 8\gamma_{\beta\alpha}^I \langle \text{tr} \psi_\beta X^I \psi_\alpha \rangle + 8\gamma_{\beta\alpha}^I \langle \text{tr} \psi_\beta \psi_\alpha X^I \rangle$$

$$0 = -16 \langle \text{tr} X^I X^I X^I X^I \rangle + 16 \langle \text{tr} X^I X^I X^I X^I \rangle - 8\gamma_{\beta\alpha}^I \langle \text{tr} \psi_\beta X^I \psi_\alpha \rangle + 8\gamma_{\beta\alpha}^I \langle \text{tr} \psi_\beta \psi_\alpha X^I \rangle$$

$$0 = \gamma_{\beta\alpha}^{II} \langle \text{tr} X^I X^I \psi_\beta \psi_\alpha \rangle - \gamma_{\beta\alpha}^{II} \langle \text{tr} \psi_\beta X^I X^I \psi_\alpha \rangle - \gamma_{\beta\alpha}^I \langle \text{tr} P^I \psi_\beta \psi_\alpha \rangle + \gamma_{\beta\alpha}^I \langle \text{tr} \psi_\beta P^I \psi_\alpha \rangle$$

$$0 = -\gamma_{\beta\alpha}^{II} \langle \text{tr} X^I X^I \psi_\beta \psi_\alpha \rangle + \gamma_{\beta\alpha}^{II} \langle \text{tr} \psi_\beta X^I X^I \psi_\alpha \rangle - \gamma_{\beta\alpha}^I \langle \text{tr} P^I \psi_\beta \psi_\alpha \rangle + \gamma_{\beta\alpha}^I \langle \text{tr} \psi_\beta P^I \psi_\alpha \rangle$$

$$0 = -\gamma_{\beta\alpha}^{II} \langle \text{tr} \psi_\beta X^I X^I \psi_\alpha \rangle + \gamma_{\beta\alpha}^{II} \langle \text{tr} \psi_\beta X^I \psi_\alpha X^I \rangle - \gamma_{\beta\alpha}^I \langle \text{tr} \psi_\beta \psi_\alpha P^I \rangle$$

$$0 = -\gamma_{\beta\alpha}^{II} \langle \text{tr} \psi_\beta X^I X^I \psi_\alpha \rangle + \gamma_{\beta\alpha}^{II} \langle \text{tr} \psi_\beta X^I \psi_\alpha X^I \rangle - \gamma_{\beta\alpha}^{II} \langle \text{tr} \psi_\beta \psi_\alpha X^I X^I \rangle$$

The hierarchy is defined by sorting operators into *levels*: we assign the basic fields  $\ell(X) = 1$ ,  $\ell(P) = 2$ , and  $\ell(\psi) = 3/2$ . The level of an operator is the sum of the levels of all its fields: schematically,  $\ell(X^{n_X} P^{n_P} \psi^{n_\psi}) = n_X + 3n_P + 3n_\psi/2$ .

- $\ell(\{Q_\alpha, \mathcal{O}_\alpha\}) = \ell(\mathcal{O}_\alpha) + \frac{1}{2}$
- To obtain the positivity conditions involving variables up to level  $\ell_{\text{cutoff}}$ , we need to select operators up to level  $\frac{1}{2}\ell_{\text{cutoff}}$  and take their inner products.

# BFSS MODEL BOOTSTRAP

level cutoff	total variables	free variables
4	11	3
5	38	4
6	140	11
7	569	18
8	2528	59
9	12077	149

For example, the level 5 free variables are:

$$\langle \text{tr} P^l P^l \rangle, \langle \text{tr} X^l X^l \rangle, \langle \text{tr} X^l X^l X^l X^l \rangle, \langle \text{tr} X^l X^l \psi_\alpha \psi_\alpha \rangle \quad (48)$$

# POSITIVITY

By Schur's lemma, operators in different irreducible representations are orthogonal to each other. We need to classify the operators with respect to their  $SO(9)$  quantum number. Here is an example from the singlet positivity:

$$\begin{array}{c}
 1 \\
 X^I X^J \\
 iP^I X^J \\
 0
 \end{array}
 \begin{pmatrix}
 1 & X^I X^I & -iX^I P^I & 0 \\
 1 & \text{tr}X^2 & 9/2 & 8 \\
 \text{tr}X^2 & \text{tr}X^2 X^2 & -i\text{tr}X^2 XP & \text{tr}X^2 O \\
 9/2 & -i\text{tr}X^2 XP & \text{tr}PXXP & i\text{tr}PXO \\
 8 & \text{tr}X^2 O & i\text{tr}PXO & \text{tr}OO
 \end{pmatrix}
 \succeq 0.$$

Here  $O = \psi_\alpha \psi_\alpha$

# NUMERICAL RESULT

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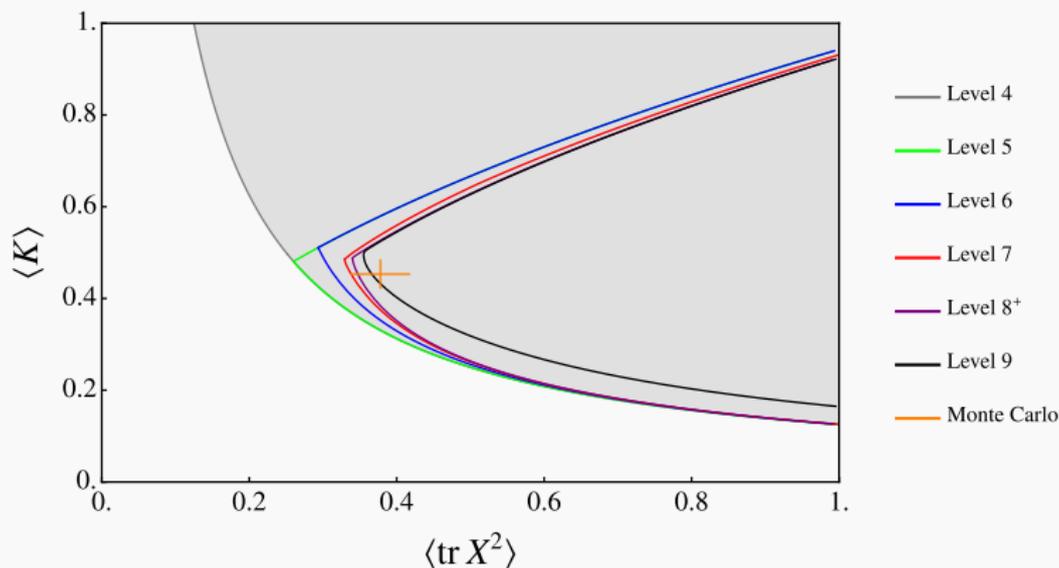
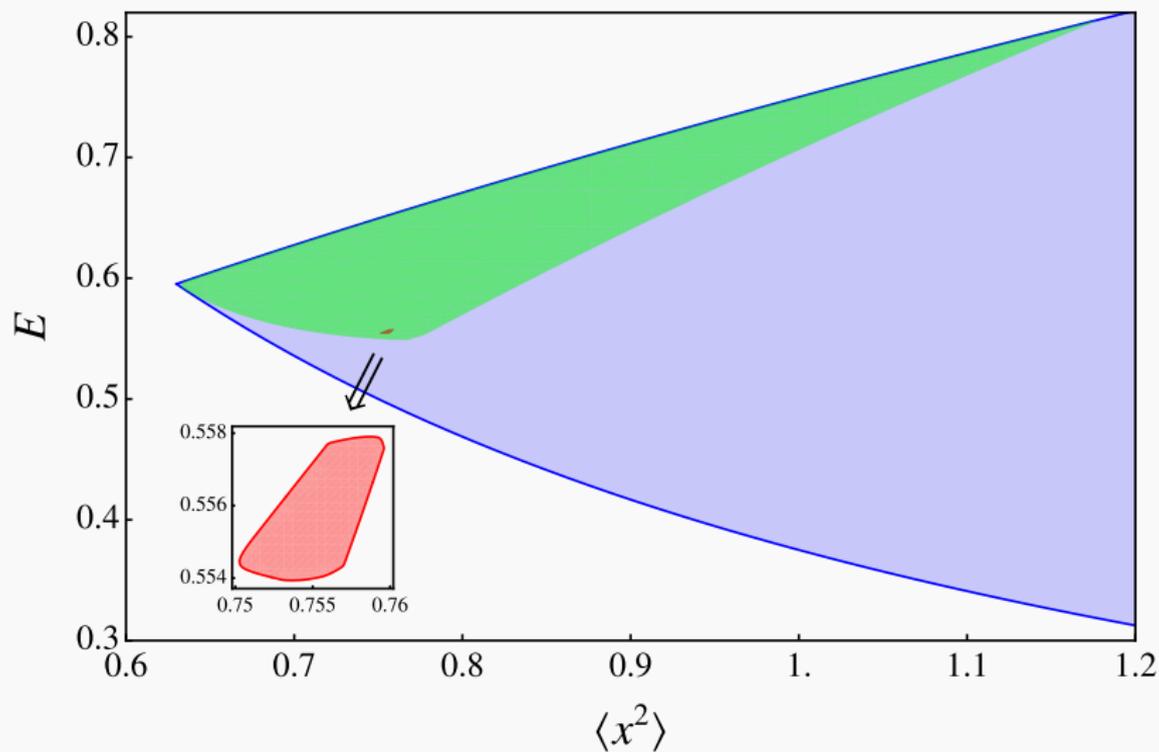


Figure 2:  $\langle K \rangle \propto \langle \text{tr} P^2 \rangle \propto \langle \text{tr}[X^l, X'^l]^2 \rangle$  We also show the extrapolation of the Monte Carlo [Berkowitz et al., 2018] results.

# CONVERGENCE

method	$\langle \text{tr}X^2 \rangle$
Monte Carlo [Berkowitz et al., 2018]	$\approx 0.378 \pm 0.04$
Monte Carlo [Pateloudis et al., 2023]	$[0.346, 0.430]$
primitive bootstrap [Lin, 2023]	$\geq 0.1875$
bootstrap level 5	$\geq 0.260$
bootstrap level 6	$\geq 0.294$
bootstrap level 7	$\geq 0.329$
bootstrap level 8 <sup>+</sup>	$\geq 0.340$
bootstrap level 9	$\geq 0.355$

# COMPARE WITH TOY MODEL



# BOSONIC BFSS MODEL

The Hamiltonian:

$$H = \frac{1}{2} \sum_{l=1}^D (\text{Tr} P^l P^l + M^2 \text{Tr} X^l X^l) - \sum_{l,j=1}^D \text{Tr} [X^l, X^j]^2 \quad (49)$$

Especially for the D=2 case, we have:

$$Z = \frac{1}{\sqrt{2}}(X + iY), \quad \bar{Z} = \frac{1}{\sqrt{2}}(X - iY), \quad (50)$$

$$P = \frac{1}{\sqrt{2}}(P_x + iP_y), \quad \bar{P} = \frac{1}{\sqrt{2}}(P_x - iP_y), \quad (51)$$

$$H = -\text{tr} \Pi \bar{\Pi} + M^2 \text{tr} Z \bar{Z} + \text{tr} [Z, \bar{Z}]^2. \quad (52)$$

# ANALYTIC BOUND

The two positivities of  $X^I$  and  $P^I$  read:

$$\begin{pmatrix} \frac{D}{2} & \text{tr}P^I P^I \\ \text{tr}P^I P^I & (D-1)\text{tr}X^I X^I + M^2 \end{pmatrix} \succeq 0 \quad (53)$$

$$\begin{pmatrix} \text{tr}X^I X^I & D/2 \\ D/2 & \text{tr}P^I P^I \end{pmatrix} \succeq 0 \quad (54)$$

Which means:

$$\frac{3}{16\langle \text{tr}X^2 \rangle} + \frac{M^2 \langle \text{tr}X^2 \rangle}{4} \leq \frac{\mathcal{E}}{D} \leq \frac{1}{8} \left[ 2M^2 \langle \text{tr}X^2 \rangle + 3 \left( 2(D-1)\langle \text{tr}X^2 \rangle + 2\frac{M^2}{D} \right)^{1/2} \right], \quad (55)$$

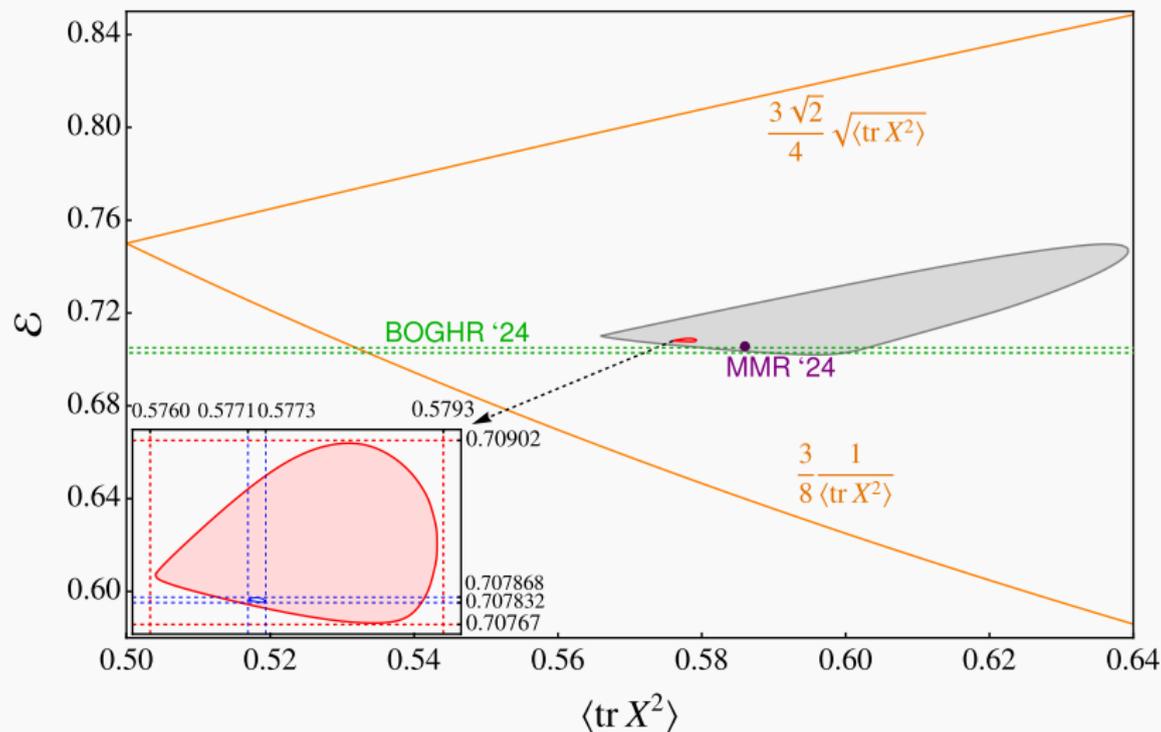
$$\mathcal{E} \equiv \frac{E_0}{N^2} (g_{\text{YM}}^2 N)^{-1/3} = \frac{3}{4} \langle \text{tr}P^I P^I \rangle + \frac{1}{4} M^2 \langle \text{tr}X^I X^I \rangle \quad (56)$$

# BENCHMARK (2507.21007)

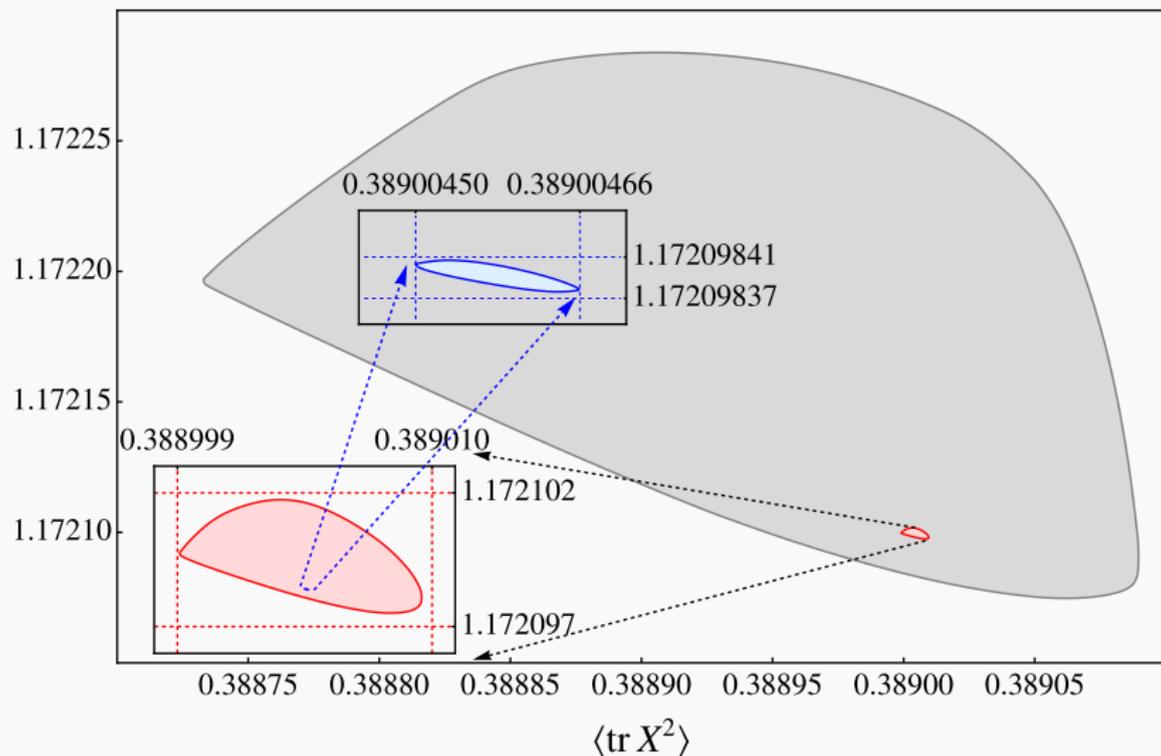
Model	$\mathcal{E}$	$\langle \text{tr} X_i X_i \rangle$	level 4 operator
$M^2 = 0, D = 2$			$\langle \text{tr}(Z^2 \bar{Z}^2) \rangle$
Bootstrap	[0.707832, 0.707868]	[1.15420, 1.15460]	[0.37055, 0.37085]
Monte Carlo	0.7039(11)	—	—
Loop truncation	0.7056(2)	1.172(1)	0.383(2)
Large $D$ expansion	0.756	0.985	0.177
$M^2 = 1, D = 2$			$\langle \text{tr}(Z^2 \bar{Z}^2) \rangle$
Bootstrap	[1.172098376, 1.172098408]	[0.77800898, 0.77800934]	[0.15850588, 0.15850607]
Monte Carlo	1.1654(11)	—	—
Loop truncation	1.17198	0.7784	0.1588
$M^2 = 0, D = 9$			$\langle \text{tr} X_i X_i X_i X_i \rangle$
Bootstrap	[6.69946, 6.69968]	[2.29195, 2.29218]	[5.7787, 5.7804]
Monte Carlo	6.695(5)	2.291(1)	—
Large $D$ expansion	6.713	2.279	5.646

**Table 1:** Ground state energy  $\mathcal{E}$  bounds and expectation values ...

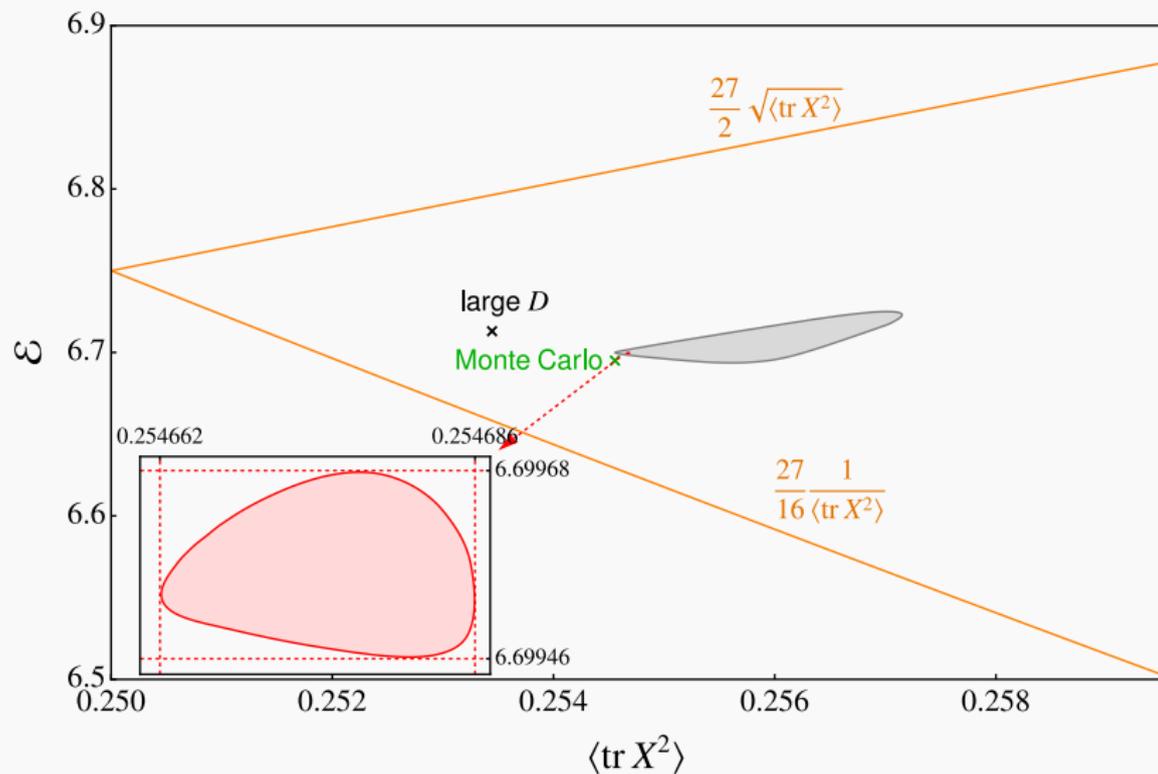
# O(2) MODEL(MASSLESS)



# O(2) MODEL ( $M^2 = 1$ )



# O(9) MODEL(MASSLESS)



# BENCHMARK (2507.21007)

Model	$\mathcal{E}$	$\langle \text{tr} X_i X_i \rangle$	level 4 operator
$M^2 = 0, D = 2$			
			$\langle \text{tr}(Z^2 \bar{Z}^2) \rangle$
Bootstrap	[0.707832, 0.707868]	[1.15420, 1.15460]	[0.37055, 0.37085]
Monte Carlo	0.7039(11)	—	—
Loop truncation	0.7056(2)	1.172(1)	0.383(2)
Large $D$ expansion	0.756	0.985	0.177
$M^2 = 1, D = 2$			
			$\langle \text{tr}(Z^2 \bar{Z}^2) \rangle$
Bootstrap	[1.172098376, 1.172098408]	[0.77800898, 0.77800934]	[0.15850588, 0.15850607]
Monte Carlo	1.1654(11)	—	—
Loop truncation	1.17198	0.7784	0.1588
$M^2 = 0, D = 9$			
			$\langle \text{tr} X_i X_i X_i X_i \rangle$
Bootstrap	[6.69946, 6.69968]	[2.29195, 2.29218]	[5.7787, 5.7804]
Monte Carlo	6.695(5)	2.291(1)	—
Large $D$ expansion	6.713	2.279	5.646

**Table 2:** Ground state energy  $\mathcal{E}$  bounds and expectation values ...

# EUCLIDEAN TWO-POINT CORRELATOR(2511.08560)

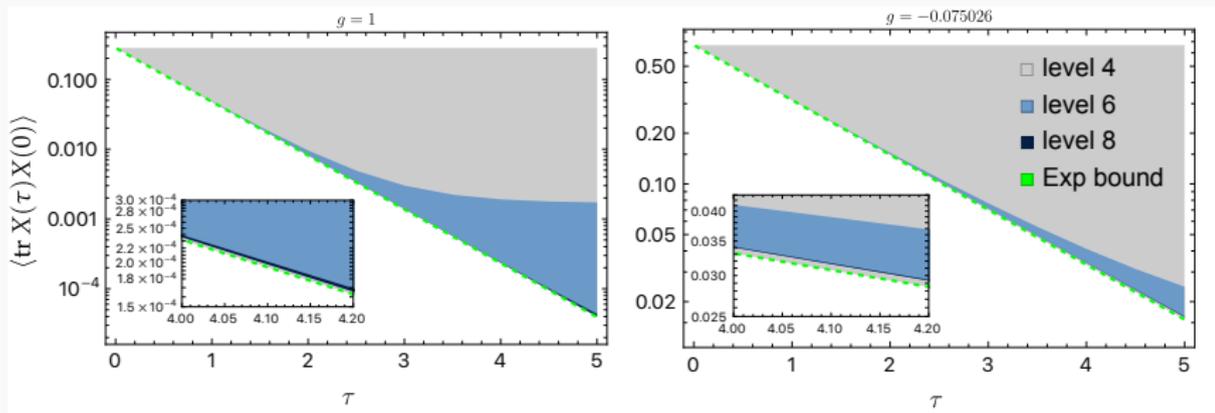


Figure 3: Euclidean two-point correlator  $\langle \text{tr} X(\tau) X(0) \rangle$  in the ground state of the 1-MQM with  $V = \frac{1}{2} \text{Tr} X^2 + g \text{Tr} X^4$  at  $g = 1$  (left) and  $g = -0.075026 \approx g_c$  (right). The shaded region indicates the allowed bootstrap region at level- $\{4, 6, 8\}$ .

# EUCLIDEAN TWO-POINT CORRELATOR(2511.08560)

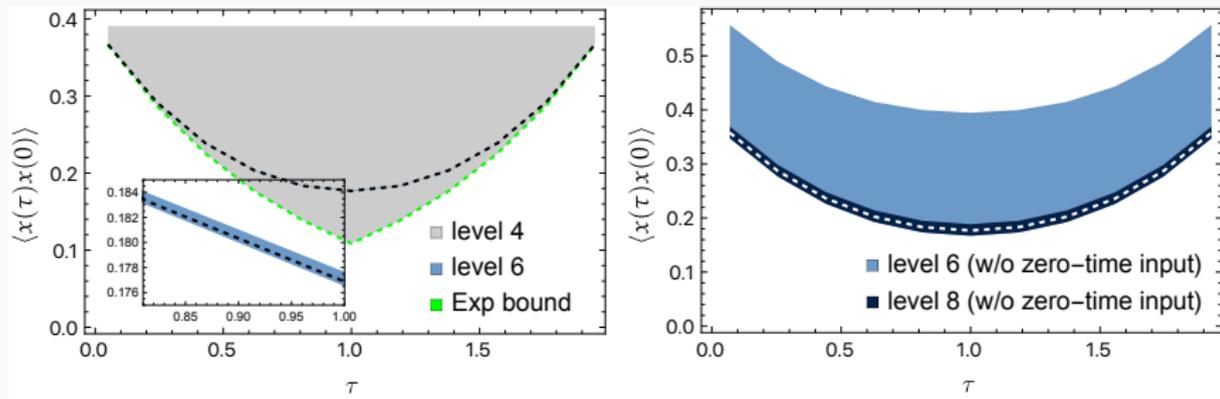


Figure 4: Bootstrap bounds on the Euclidean two-point correlator in the thermal state of anharmonic oscillator with  $H = \frac{1}{2}x^2 + \frac{1}{2}p^2 + \frac{1}{4}x^4$  at  $\beta = 2$ .

# EUCLIDEAN TWO-POINT CORRELATOR(2511.08560)

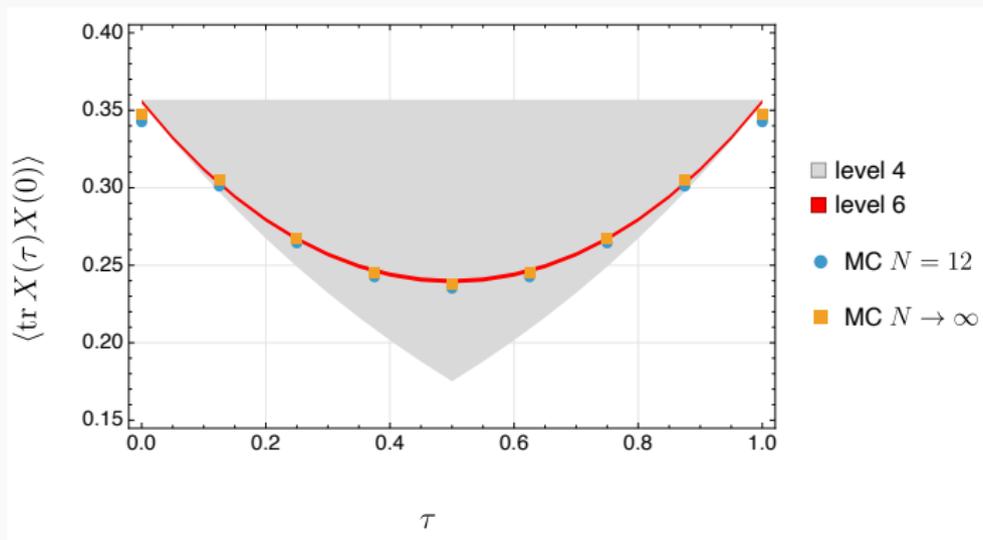


Figure 5: Bootstrap bounds on the thermal two-point correlator  $\langle \text{tr} X(\tau) X(0) \rangle$  for the ungauged 1-MQM with  $\beta = 1$  and  $g = 1$ , at levels 4 and 6.

# EUCLIDEAN TWO-POINT CORRELATOR(2511.08560)

This is simply a condition on the connected two-point correlator  $G_c(\tau) = \langle \bar{\mathcal{O}}(\tau)\mathcal{O}(0) \rangle - \langle \bar{\mathcal{O}} \rangle \langle \mathcal{O} \rangle$ . By the inner product of  $\{\mathcal{O}, [H, \mathcal{O}]\}$  at  $\frac{\tau}{2}$  and  $-\frac{\tau}{2}$

$$\mathcal{M}_c(\tau) = \begin{pmatrix} G_c(\tau) & G'_c(\tau) \\ G'_c(\tau) & G''_c(\tau) \end{pmatrix} \succeq 0 \implies (\log G_c(\tau))'' \geq 0. \quad (57)$$

$$\log G_c(\tau) \geq \log G_c(0) + \tau \frac{G'_c(0^+)}{G_c(0)} \implies G_c(\tau) \geq G_c(0) \exp(-\mu\tau), \quad (58)$$

$$\mu = \frac{-G'_c(0^+)}{G_c(0)}. \quad (59)$$

# EUCLIDEAN TWO-POINT CORRELATOR(2511.08560)

$$\log G_c(\tau) \geq \log G_c(0) + \tau \frac{G'_c(0^+)}{G_c(0)} \quad (60)$$

$$\log \frac{G(\beta)}{G(0)} \geq \beta \frac{G'(0)}{G(0)}. \quad (61)$$

$$G(0) = \langle \mathcal{O}^\dagger \mathcal{O} \rangle_\beta, \quad G'(0) = -\langle \mathcal{O}^\dagger [H, \mathcal{O}] \rangle_\beta \quad (62)$$

$$G(\beta) = \text{tr}\{\rho e^{\beta H} \mathcal{O}^\dagger e^{-\beta H} \mathcal{O}\} = \text{tr}\{\mathcal{O} \mathcal{O}^\dagger \rho\} = \langle \mathcal{O} \mathcal{O}^\dagger \rangle_\beta. \quad (63)$$

In the last line we used the KMS condition. Plugging into (61), we arrive at the Energy-Entropy balance (EEB) inequality [Araki and Sewell, 1977]:

$$\langle \mathcal{O}^\dagger \mathcal{O} \rangle \log \frac{\langle \mathcal{O}^\dagger \mathcal{O} \rangle}{\langle \mathcal{O} \mathcal{O}^\dagger \rangle} \leq \beta \langle \mathcal{O}^\dagger [H, \mathcal{O}] \rangle, \quad \forall \mathcal{O} \quad (64)$$

# EUCLIDEAN TWO-POINT CORRELATOR(2511.08560)

$$\begin{aligned} & \text{minimize } \langle x(T)x(0) \rangle, \\ & \text{subject to } \mathcal{M}(\tau) = \begin{pmatrix} \langle x(\tau)x(0) \rangle & -i\langle x(\tau)p(0) \rangle \\ -i\langle x(\tau)p(0) \rangle & \langle p(\tau)p(0) \rangle \end{pmatrix} \succeq 0, \end{aligned} \quad (65)$$

with the prototype:

$$\begin{aligned} & \text{minimize } \text{Tr } \widehat{O}\mathcal{M}(T) \\ & \text{subject to } \mathcal{M}(\tau) \succeq 0 \\ & \quad \text{Tr} \left( D^{(k)} - C^{(k)} \frac{d}{d\tau} \right) \mathcal{M}(\tau) = 0. \end{aligned} \quad (66)$$

# EUCLIDEAN TWO-POINT CORRELATOR(2511.08560)

$$\begin{aligned} & \text{minimize } \text{Tr } \widehat{O} \mathcal{M}(T) \\ & \text{subject to } \mathcal{M}(\tau) \succeq 0 \end{aligned} \tag{67}$$

$$\text{Tr} \left( D^{(k)} - C^{(k)} \frac{d}{d\tau} \right) \mathcal{M}(\tau) = 0.$$

$$\mathcal{O} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \tag{68}$$

$$C^{(1)} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \quad C^{(2)} = \begin{pmatrix} 0 & 1/2 \\ 1/2 & 0 \end{pmatrix}, \tag{69}$$

$$D^{(1)} = \begin{pmatrix} 0 & -1/2 \\ -1/2 & 0 \end{pmatrix}, \quad D^{(2)} = \begin{pmatrix} 0 & 0 \\ 0 & -1 \end{pmatrix}, \tag{70}$$

$$\mathcal{M}(0) = \begin{pmatrix} \langle x^2 \rangle & 1/2 \\ 1/2 & \langle p^2 \rangle \end{pmatrix}. \tag{71}$$

# EUCLIDEAN TWO-POINT CORRELATOR(2511.08560)

$$\begin{aligned} & \text{minimize } \text{Tr } \widehat{O} \mathcal{M}(T) \\ & \text{subject to } \mathcal{M}(\tau) \succeq 0 \\ & \text{Tr} \left( D^{(k)} - C^{(k)} \frac{d}{d\tau} \right) \mathcal{M}(\tau) = 0. \end{aligned} \tag{72}$$

$$\begin{aligned} I &= \text{Tr} \left\{ \widehat{O} \mathcal{M}(T) + \int_0^T d\tau \left[ \lambda_D^{(k)} \left( D^{(k)} - C^{(k)} \partial_\tau \right) - \Lambda_{\mathcal{M}} \right] \mathcal{M}(\tau) \right\} \\ &= \text{Tr} \left\{ \int_0^T d\tau \left[ \left( D^{(k)} + C^{(k)} \frac{d}{d\tau} \right) \lambda_D^{(k)} - \Lambda_{\mathcal{M}} \right] \mathcal{M}(\tau) + \left[ \widehat{O} - \lambda_D^{(k)}(T) C^{(k)} \right] \mathcal{M}(T) \right\} \end{aligned}$$

# EUCLIDEAN TWO-POINT CORRELATOR(2511.08560)

$$\begin{aligned}
 & \text{minimize } \text{Tr } \widehat{O} \mathcal{M}(T) \\
 & \text{subject to } \mathcal{M}(\tau) \succeq 0 \\
 & \text{Tr} \left( D^{(k)} - C^{(k)} \frac{d}{d\tau} \right) \mathcal{M}(\tau) = 0.
 \end{aligned} \tag{73}$$

$$\begin{aligned}
 I &= \text{Tr} \left\{ \widehat{O} \mathcal{M}(T) + \int_0^T d\tau \left[ \lambda_D^{(k)} \left( D^{(k)} - C^{(k)} \partial_\tau \right) - \Lambda_{\mathcal{M}} \right] \mathcal{M}(\tau) \right\} \\
 &= \text{Tr} \left\{ \int_0^T d\tau \left[ \left( D^{(k)} + C^{(k)} \frac{d}{d\tau} \right) \lambda_D^{(k)} - \Lambda_{\mathcal{M}} \right] \mathcal{M}(\tau) + \left[ \widehat{O} - \lambda_D^{(k)}(T) C^{(k)} \right] \mathcal{M}(T) \right\}
 \end{aligned}$$

$$\begin{aligned}
 & \text{maximize } \lambda_D^{(k)}(0) \text{Tr } C^{(k)} \mathcal{M}(0) \\
 & \text{subject to } \widehat{O} - \lambda_D^{(k)}(T) C^{(k)} = 0 \\
 & \left( D^{(k)} + C^{(k)} \partial_\tau \right) \lambda_D^{(k)}(\tau) \succeq 0
 \end{aligned} \tag{74}$$

# EUCLIDEAN TWO-POINT CORRELATOR(2511.08560)

$$\begin{aligned} & \text{minimize} \quad \langle x(T)x(0) \rangle, \\ & \text{subject to} \quad \mathcal{M}(\tau) = \begin{pmatrix} \langle x(\tau)x(0) \rangle & -i\langle x(\tau)p(0) \rangle \\ -i\langle x(\tau)p(0) \rangle & \langle p(\tau)p(0) \rangle \end{pmatrix} \succeq 0, \end{aligned} \quad (75)$$

dual to:

$$\begin{aligned} & \text{maximize} \quad \lambda_D^{(1)}(0)\langle x^2 \rangle + \frac{1}{2}\lambda_D^{(2)}(0), \\ & \text{subject to} \quad \begin{pmatrix} \lambda_D^{(1)}(T) & \lambda_D^{(2)}(T)/2 \\ \lambda_D^{(2)}(T)/2 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \\ & \quad \begin{pmatrix} \lambda_D^{\prime(1)}(\tau) & \lambda_D^{\prime(2)}(\tau)/2 \\ \lambda_D^{\prime(2)}(\tau)/2 & 0 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_D^{(1)}(\tau)/2 \\ \lambda_D^{(1)}(\tau)/2 & \lambda_D^{(2)}(\tau) \end{pmatrix} \succeq 0. \end{aligned} \quad (76)$$

- Other systems with sign-problem: Yang-Mills with theta terms, IKKT model...
- Gauged matrix model, subleading in  $\frac{1}{N}$
- Lorentzian-time correlator, complex-time correlator
- S-matrix and the BFSS conjecture

Questions?

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