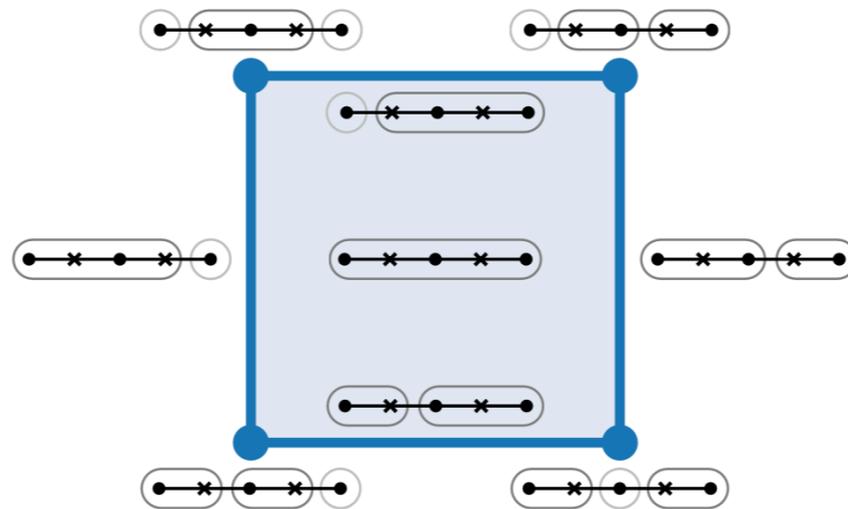


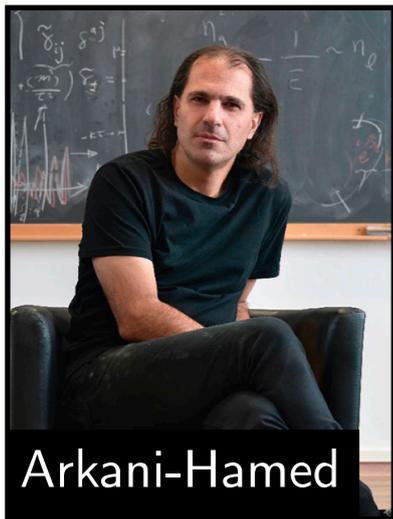
# A Hidden Pattern in Cosmological Correlators



Hayden Lee

University of Pennsylvania

This is based on work with:



Arkani-Hamed

IAS



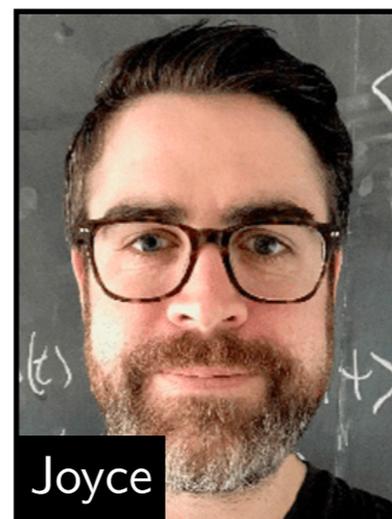
Baumann

Amsterdam



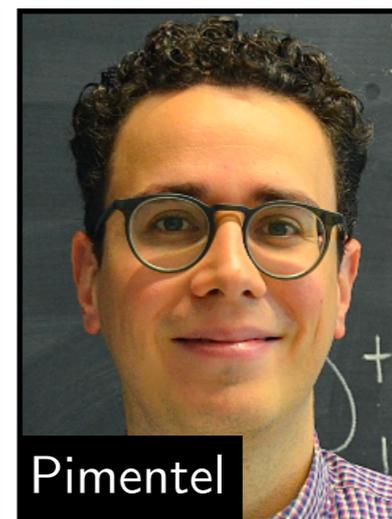
Hillman

Caltech



Joyce

Chicago



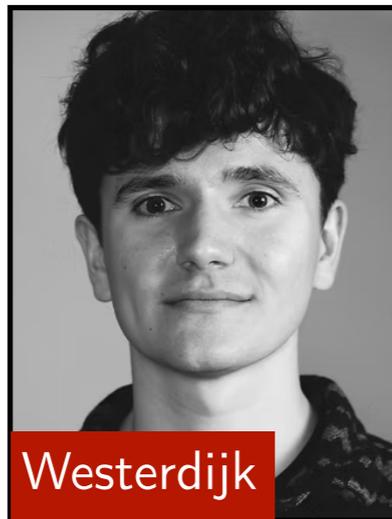
Pimentel

SNS



Goodhew

NTU



Westerdijk

SNS



Salehi Vaziri

Amsterdam



Benincasa

IGFAE

Massive Kinematic Flow [work in progress]

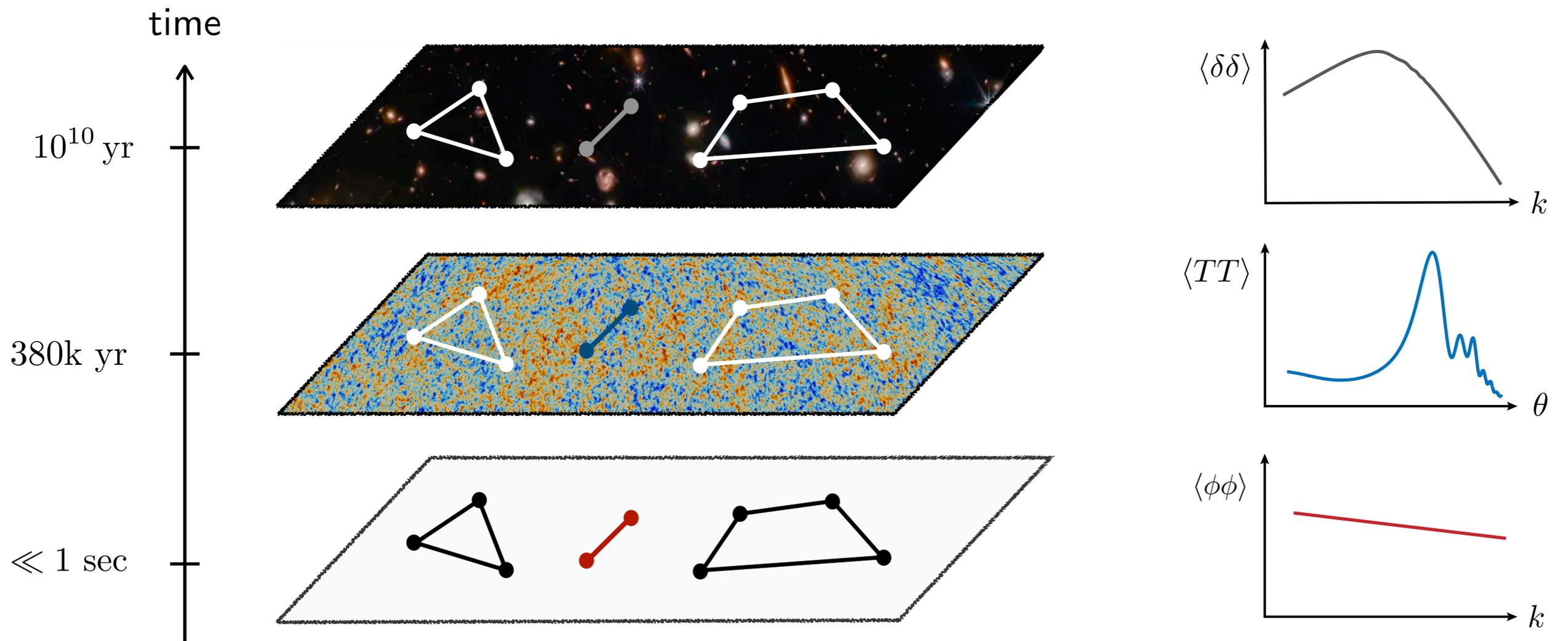
Geometry of Kinematic Flow [2504.14890]

Kinematic flow for cosmological loop integrands [2410.17994]

Kinematic Flow and the Emergence of Time [2312.05300]

Differential Equations for Cosmological Correlators [2312.05303]

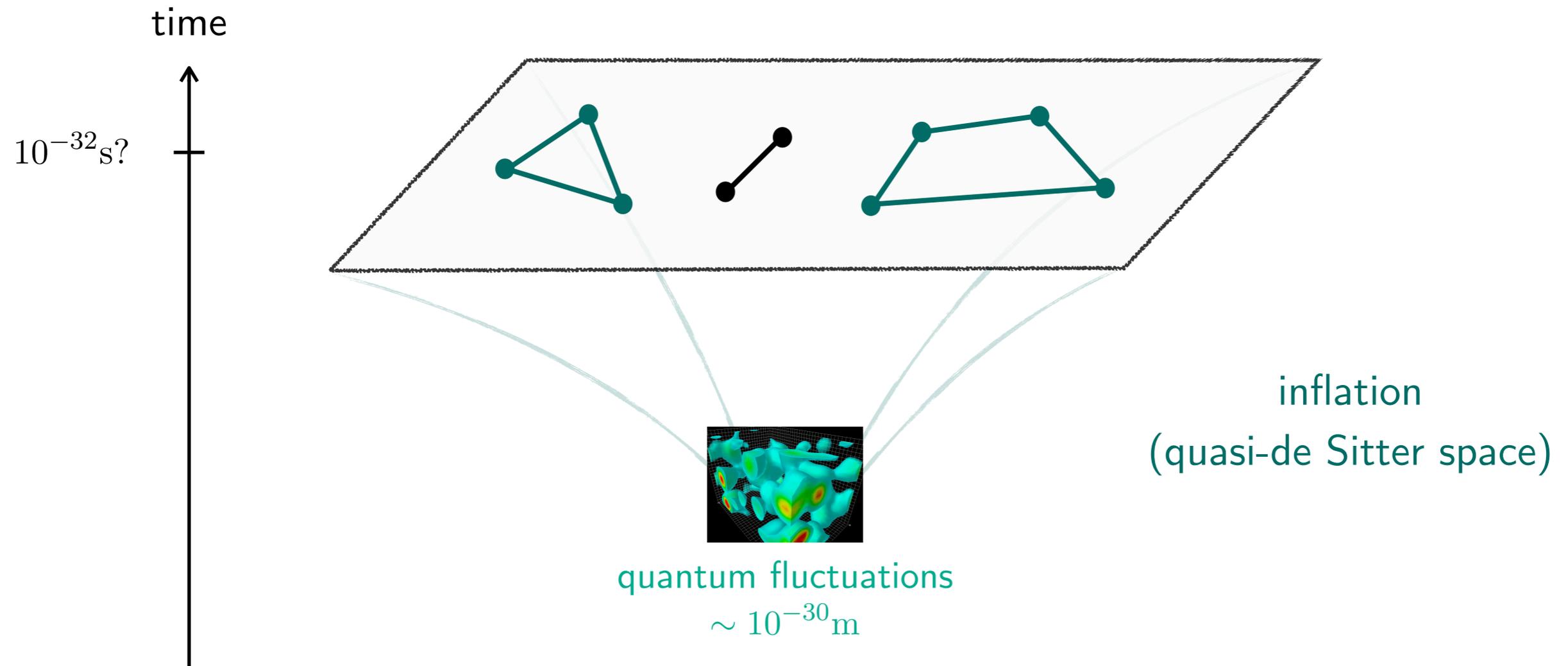
# Cosmological Correlations



By measuring cosmological correlations, we learn both about the **evolution** of the Universe and its **initial conditions**.

[See also G. Pimentel's talk]

# Inflationary Correlations

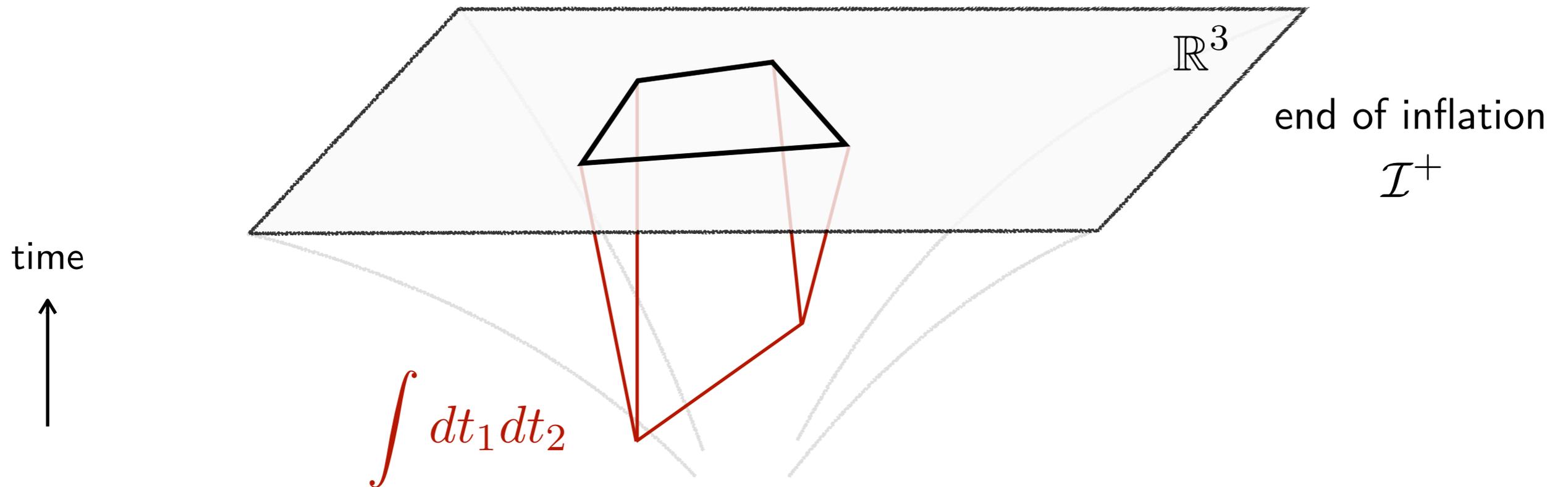


During **inflation**, correlators arise from **quantum fluctuations**.

Dynamical information is encoded in **higher-point correlations**.

# Direct Calculation

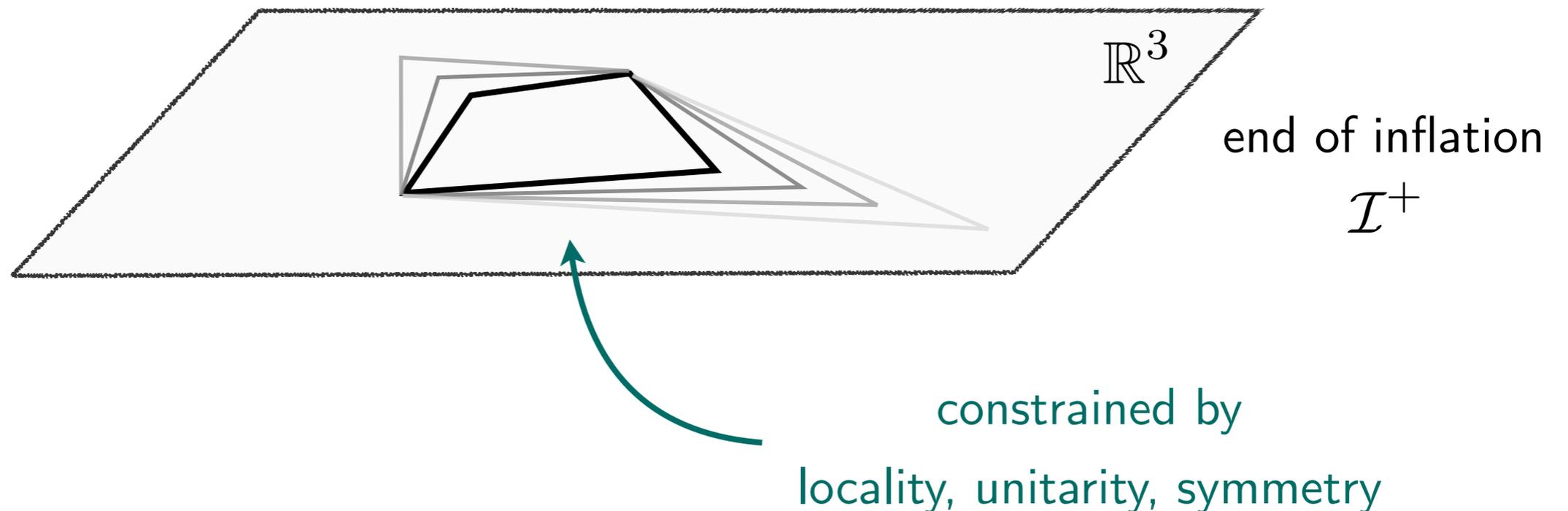
In the standard approach, correlators are computed with **time integrals**.



While the relevant **time integrals** are hard to compute,  
the **final answers** are often remarkably simple.

# Bootstrap Approach

**Goal:** to directly **bootstrap** correlators on the spatial boundary.

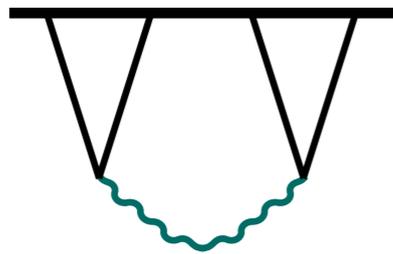


practical advantage: **simplifies** computations

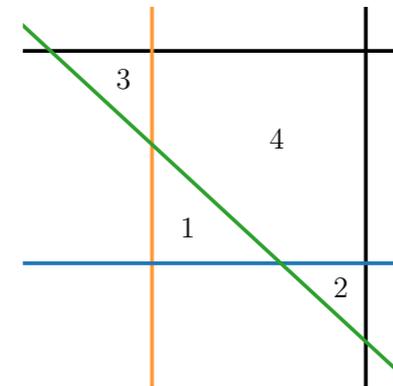
conceptual advantage: reveals **hidden structures**

# Outline

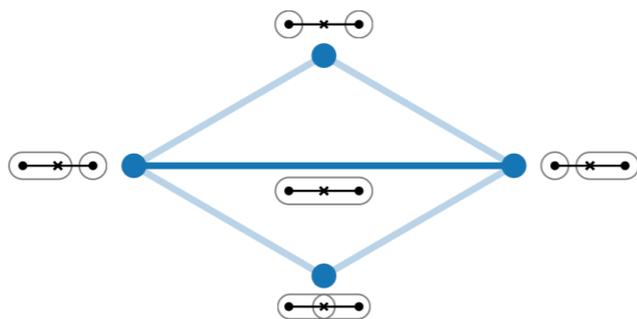
## 1. Correlators in dS



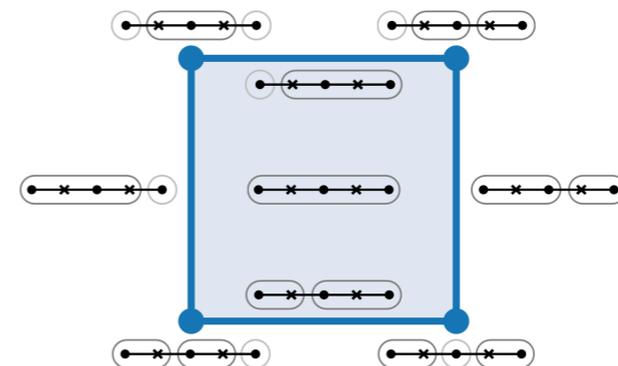
## 2. Correlators in Toy Universe



## 4. A Hidden Pattern in dS

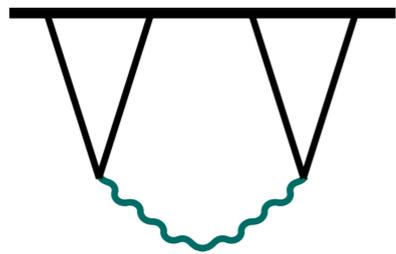


## 3. A Hidden Pattern in Toy Universe

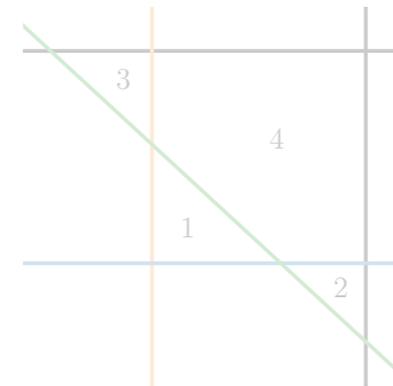


# Outline

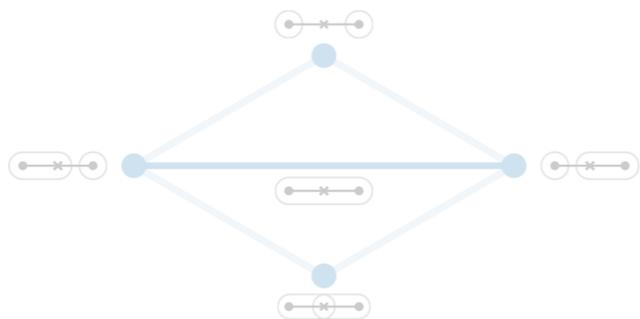
## 1. Correlators in dS



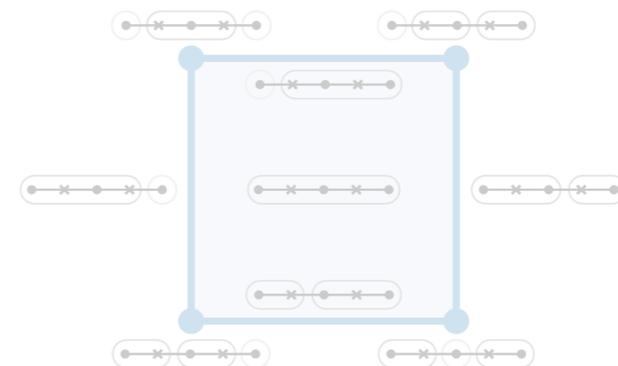
## 2. Correlators in Toy Universe



## 4. A Hidden Pattern in dS



## 3. A Hidden Pattern in Toy Universe



# Symmetries in dS

Boundary correlators in dS are constrained by the conformal group  $SO(4,1)$ .

$$\langle \phi_{\vec{k}_1} \phi_{\vec{k}_2} \phi_{\vec{k}_3} \phi_{\vec{k}_4} \rangle = \psi(\vec{k}_1, \dots, \vec{k}_4) \delta^{(3)}(\vec{k}_1 + \dots + \vec{k}_4)$$

- 3 translations
  - 3 rotations
- } momentum conservation in Fourier space  
 $\psi$  is a function of “energy” variables  $k_i = |\vec{k}_i|$
- 1 dilatation
  - 3 SCTs
- }  $D = \vec{k} \cdot \vec{\partial}_k + 3 - \Delta$   
 $\vec{K} = \vec{k}(\vec{\partial}_k \cdot \vec{\partial}_k) - 2(\vec{k} \cdot \vec{\partial}_k + 3 - \Delta)\vec{\partial}_k$

$$[m^2 = \Delta(3 - \Delta)H^2]$$

# Conformal Symmetry

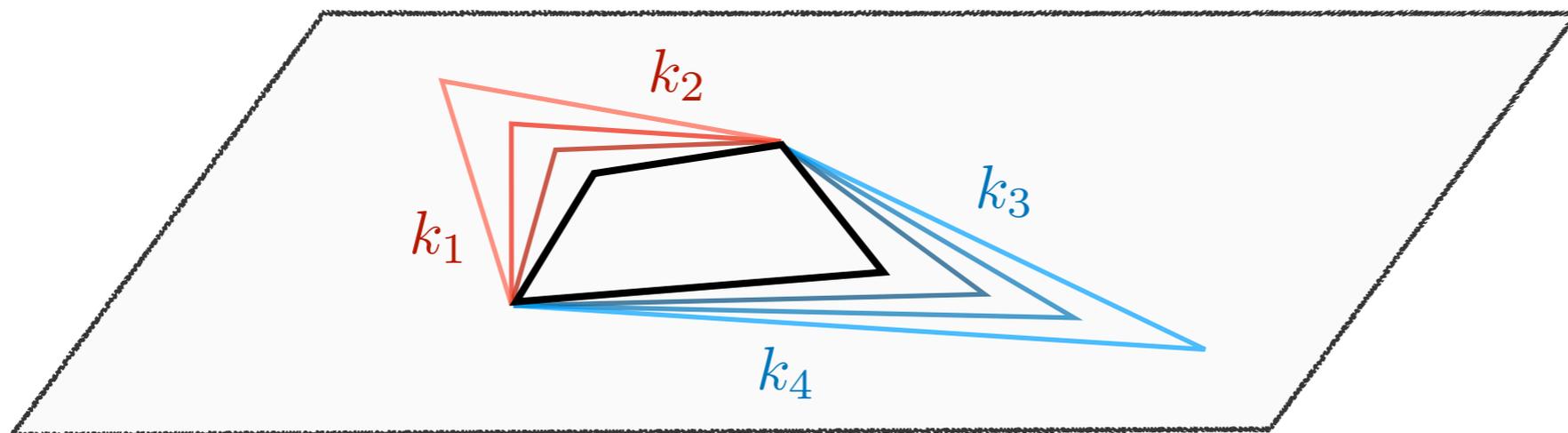
For conformally coupled scalars, the **conformal Ward identity** takes the form

$$(\Delta_{X_1} - \Delta_{X_2})\psi = 0$$

conformal Casimir

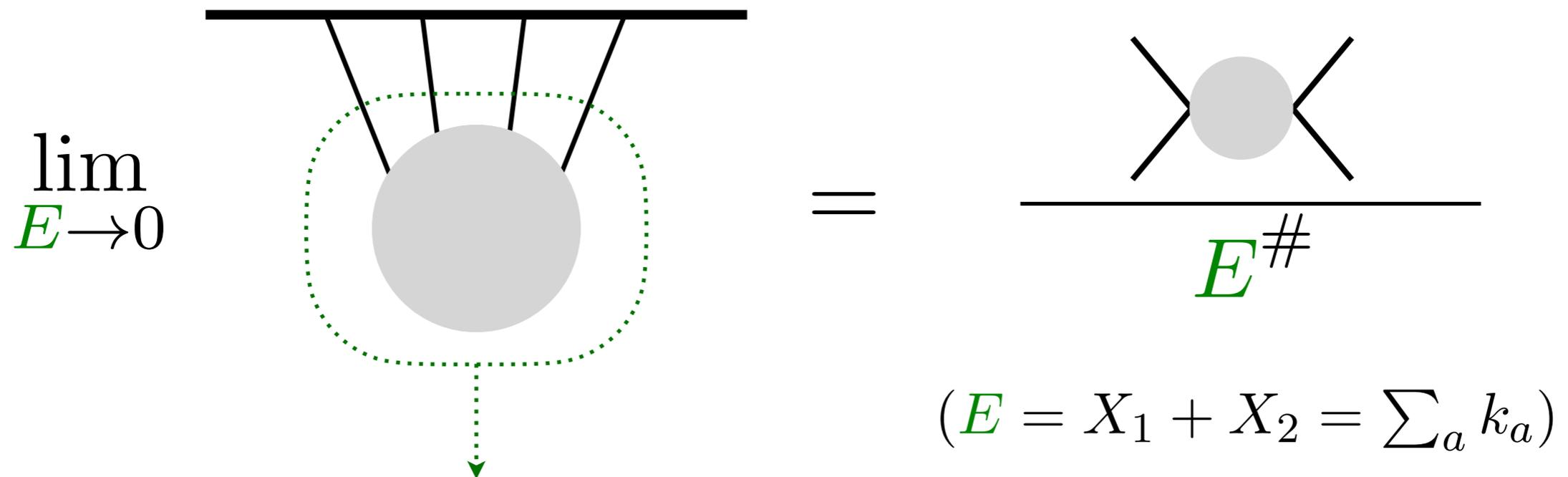
$$\Delta_X = (X^2 - 1)\partial_X^2 - 2X\partial_X$$
$$X_1 \equiv k_1 + k_2 \quad X_2 \equiv k_3 + k_4$$

This determines the strength of the correlation as its shape is deformed.



# Singularity

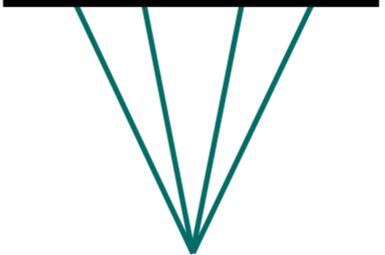
Cosmological correlators have a singularity when the **total energy** vanishes.



Amplitudes thus live in a kinematic subspace of cosmological correlators.

# Tree-Level Correlators

Contact diagrams have the simplest analytic structure.

$$(\Delta_{X_1} - \Delta_{X_2}) \frac{1}{X_1 + X_2} = 0 \quad \Rightarrow \quad \text{Diagram} \quad = \quad \sum_n c_n \Delta_{X_1}^n \left( \frac{1}{X_1 + X_2} \right)$$


This is the analog of

$$\text{Diagram} \quad = \quad \sum_n c_n s^n$$


# Tree-Level Correlators

Exchange diagrams have contact diagrams as the source term.

$$\lim_{\mu \rightarrow \infty} \psi_{\text{ex}} = \frac{1}{\mu^2} \psi_{\text{con}} \quad \Rightarrow \quad \begin{matrix} (\Delta_{X_1} - \mu^2) \\ (\Delta_{X_2} - \mu^2) \end{matrix} \begin{array}{c} \text{---} \\ \diagdown \quad \diagup \\ \text{---} \end{array} = \begin{array}{c} \text{---} \\ \diagdown \quad \diagup \\ \text{---} \end{array}$$

$$[\mu^2 = m^2 / H^2]$$

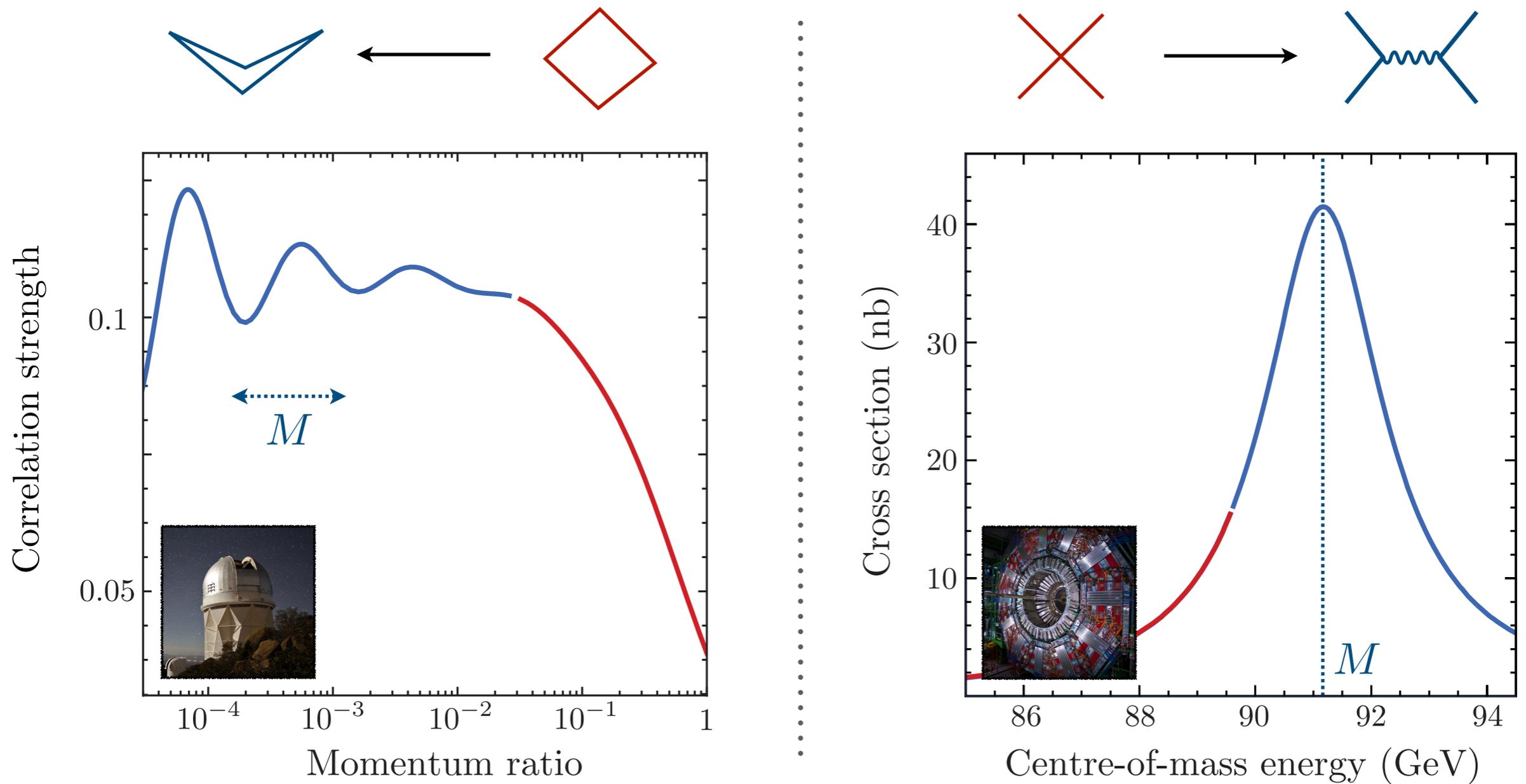

---

This is the analog of

$$\begin{matrix} (s_{12} - M^2) \\ (s_{34} - M^2) \end{matrix} \begin{array}{c} \diagup \quad \diagdown \\ \text{---} \\ \diagdown \quad \diagup \end{array} = \begin{array}{c} \diagup \quad \diagdown \\ \diagdown \quad \diagup \end{array}$$

# Cosmological Collider Physics

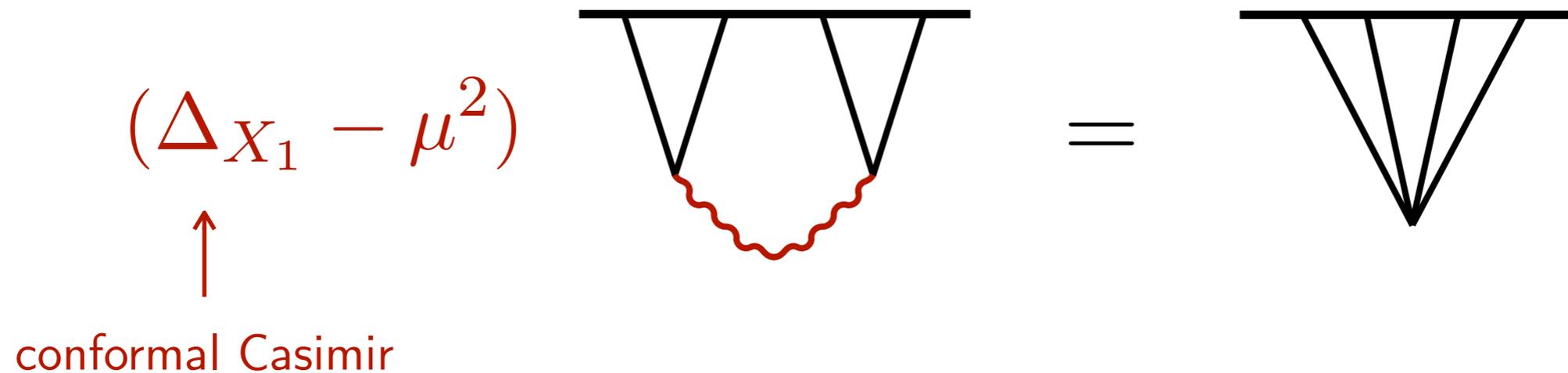
The solution captures the effect of **particle production** during inflation.



[See also Z. Xianyu's and S. Aoki's talks]

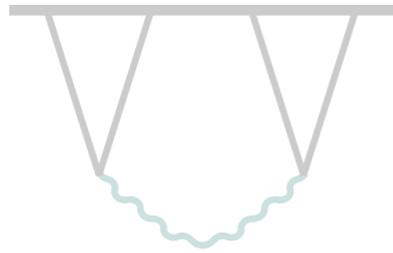
# Boundary Equations Beyond dS?

In dS, **conformal symmetry** leads to **differential equations** satisfied by boundary correlators.

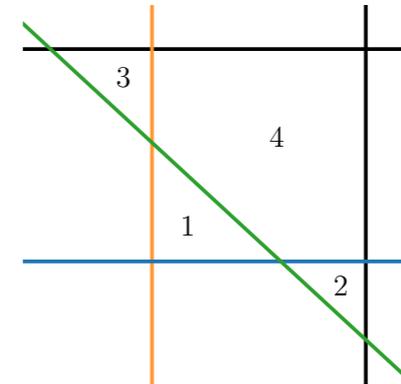


Are there similar boundary equations **beyond exact dS**?

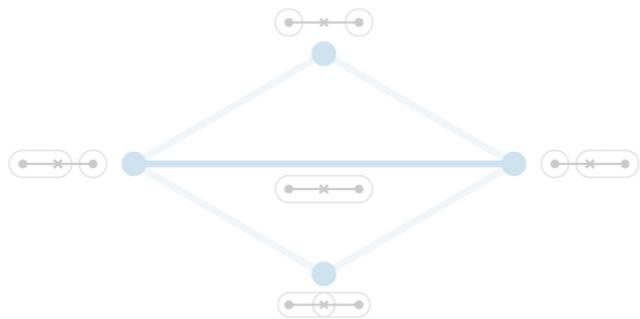
## 1. Correlators in dS



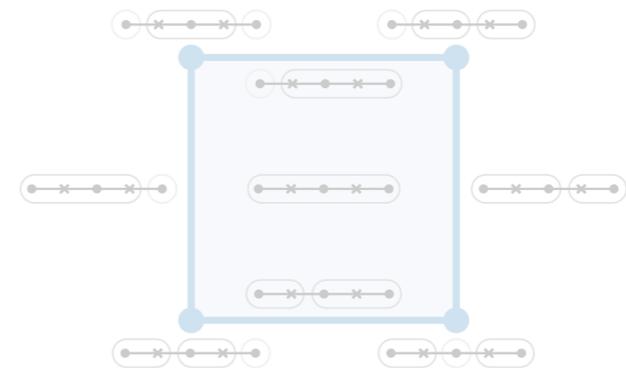
## 2. Correlators in Toy Universe



## 4. A Hidden Pattern in dS



## 3. A Hidden Pattern in Toy Universe

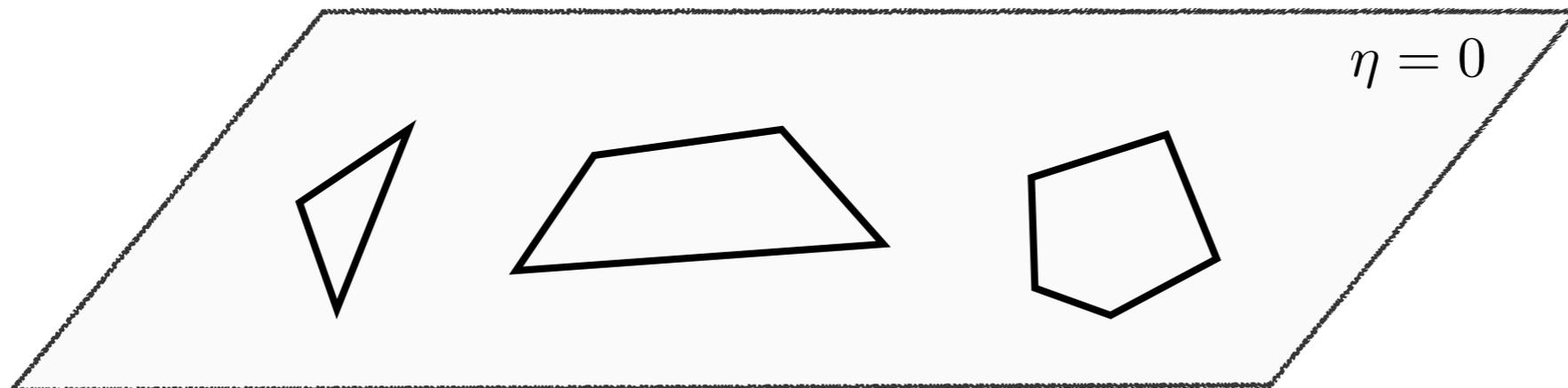


# Power-Law Cosmology

Consider an FRW spacetime expanding as a **power law**:

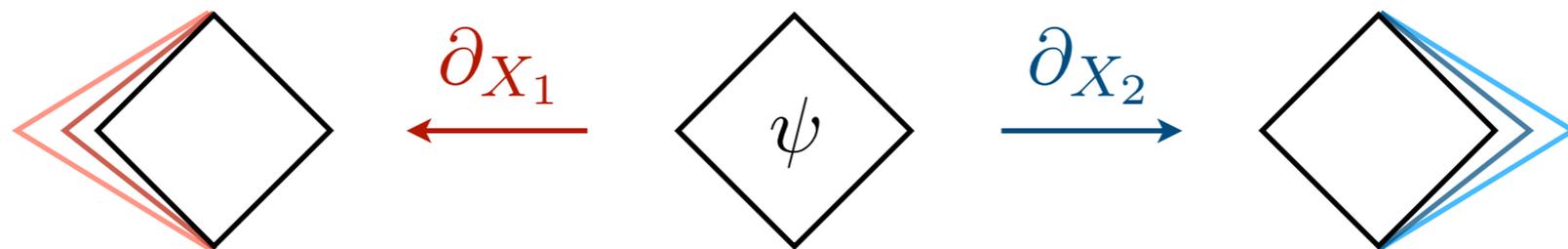
$$ds^2 = a^2(\eta)[-d\eta^2 + d\vec{x}^2] \quad a(\eta) \propto \frac{1}{\eta^{1+\varepsilon}} \quad \left\{ \begin{array}{l} \varepsilon = 0: \text{ dS} \\ \varepsilon = -1: \text{ flat} \\ \varepsilon = -2: \text{ radiation} \\ \varepsilon = -3: \text{ matter} \end{array} \right.$$

We will study general n-point functions in this spacetime.

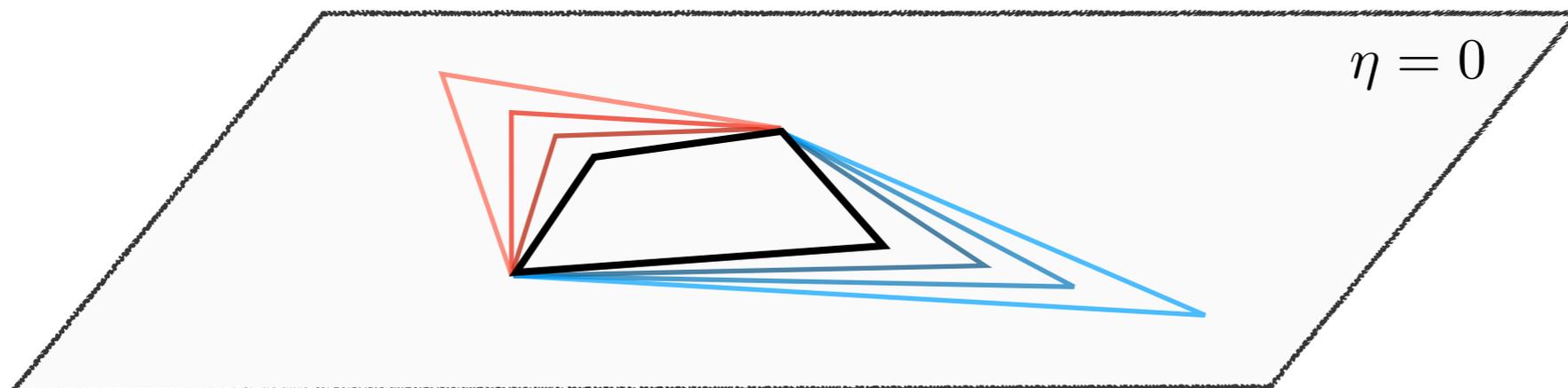


# Differential Equations

The goal is to derive the differential equations in kinematic space.



This determines the strength of the correlation as its shape is deformed.



# Toy Model

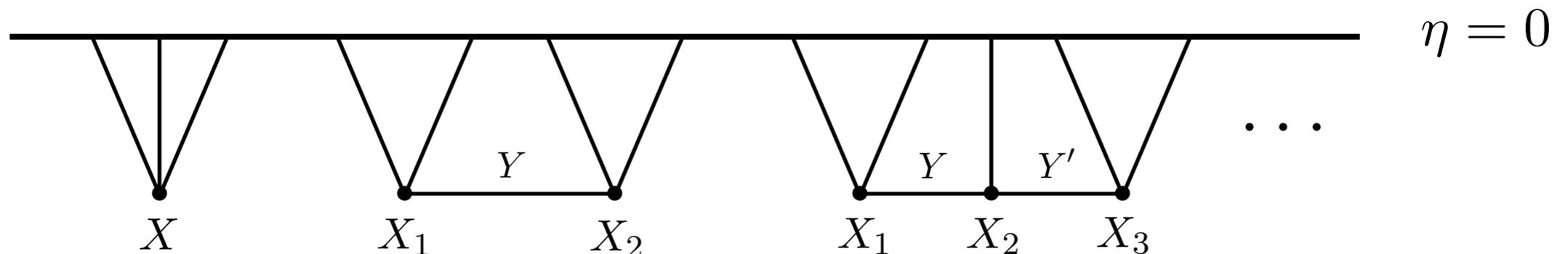
Consider a conformally coupled scalar with polynomial interactions:

$$S = \int d^4x \sqrt{-g} \left[ -\frac{1}{2} (\partial\phi)^2 - \frac{1}{12} R\phi^2 - \frac{\lambda}{3!} \phi^3 \right] \quad a(\eta) \propto \frac{1}{\eta^{1+\epsilon}}$$

conformal mass

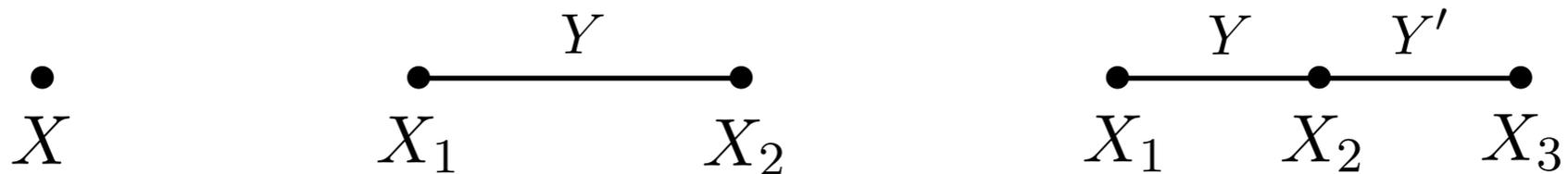
non-conformal interaction

In perturbation theory, correlators can be computed using Feynman rules.



# Graphs

Correlators can be represented by graphs with truncated external lines.



In the standard approach, these are computed from time integrals:

$$\underbrace{\bullet \text{---} \bullet \text{---} \dots \text{---} \bullet}_{\substack{v \text{ vertices} \\ e \text{ edges}}} = \int_{-\infty}^0 \prod_v d\eta_v e^{iX_v \eta_v} \prod_e G_{Y_e}(\eta_{v_e}, \eta_{v'_e})$$

$$G_Y(\eta, \eta') = \frac{1}{2Y} \left[ e^{-iY(\eta-\eta')} \theta(\eta - \eta') + \eta \leftrightarrow \eta' - e^{iY(\eta+\eta')} \right]$$

# Correlators in Flat Space

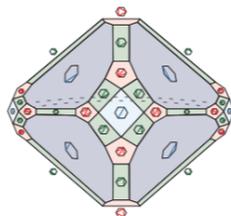
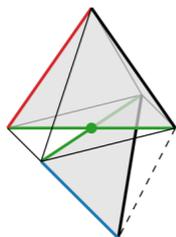
In flat space, results of time integrals can be reproduced from **graph tubings**:

$$\psi_{\text{flat}}^{(2)} = \text{Diagram} = \frac{1}{(X_1 + X_2)(X_1 + Y)(X_2 + Y)}$$


$$\psi_{\text{flat}}^{(3)} = \text{Diagram 1} + \text{Diagram 2} = \frac{1}{(X_1 + X_2 + X_3)(X_1 + Y)(X_2 + Y + Y')(X_3 + Y')} \left( \frac{1}{X_1 + X_2 + Y'} + \frac{1}{X_2 + X_3 + Y} \right)$$

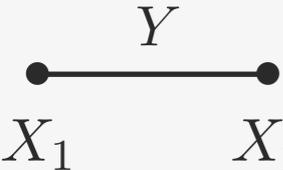

This originates from interesting **combinatorial** & **geometrical** structures

(“cosmological polytopes”, “cosmohedra”).



# Correlators in FRW

In **FRW**, the correlators are given by integrals of the flat-space results.



A diagram showing two points,  $X_1$  and  $X_2$ , connected by a horizontal line. Above the line is the label  $Y$ .

$$= \int_0^\infty dx_1 dx_2 \frac{(x_1 x_2)^\epsilon}{(X_1 + x_1 + Y)(X_2 + x_2 + Y)(X_1 + X_2 + x_1 + x_2)}$$

depends on cosmology

flat-space correlator

This integral is not so trivial! How do we do integrals of this type?

# Family of Integrals

It turns out to be useful to consider the most general integral with the same singularities:

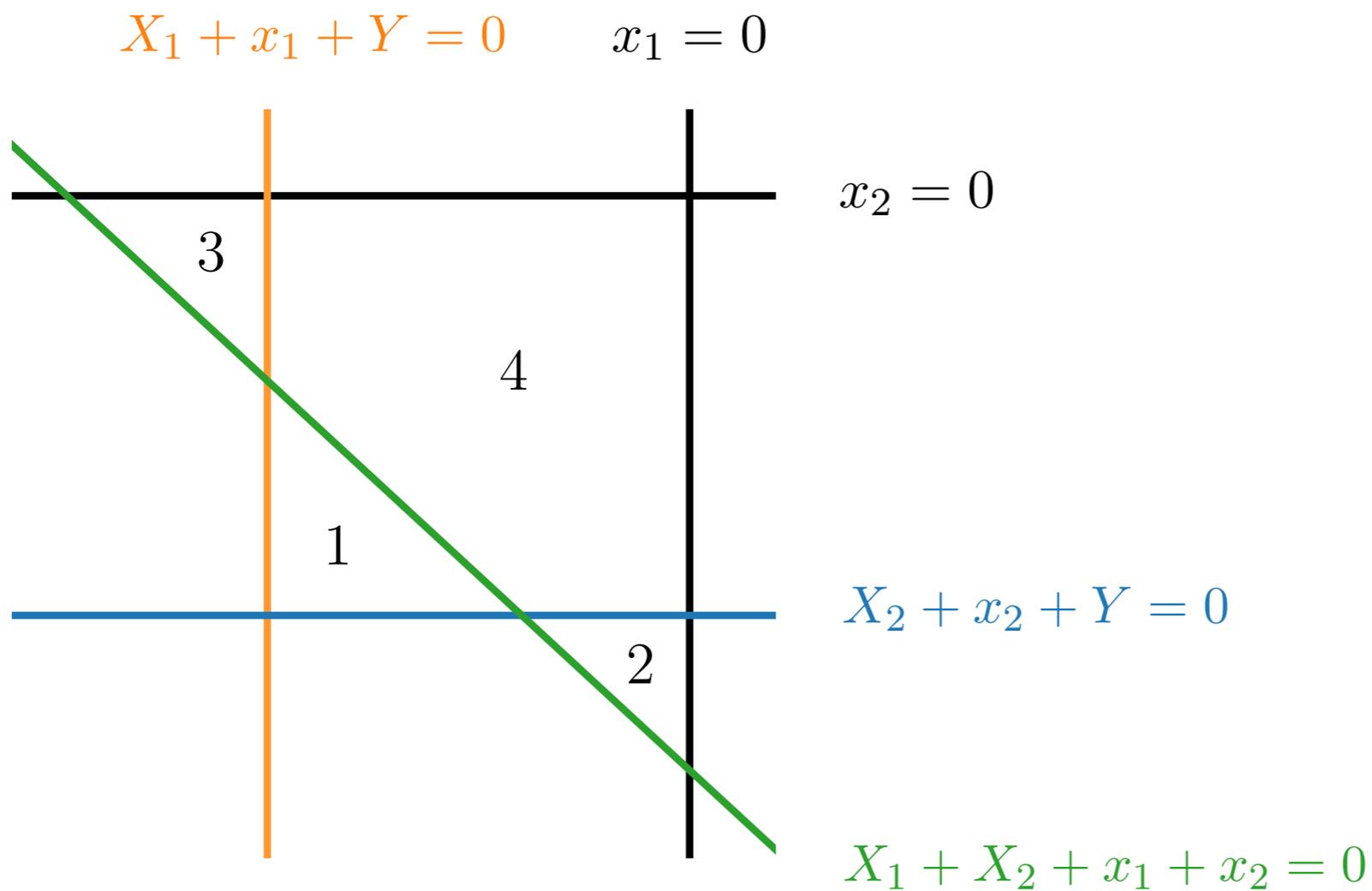
$$I_{n_1 \dots n_5} = \int_0^\infty dx_1 dx_2 \frac{x_1^{\varepsilon+n_1} x_2^{\varepsilon+n_2}}{(X_1 + x_1 + Y)^{n_3} (X_2 + x_2 + Y)^{n_4} (X_1 + X_2 + x_1 + x_2)^{n_5}} \quad (n_i \in \mathbb{Z})$$

Lesson from amplitudes: these integrals belong to a **finite** vector space and satisfy a **differential equations** of the form

$$d\vec{I} = \varepsilon A \vec{I}$$

# Hyperplanes

FRW integrals are naturally associated to hyperplane arrangements.



# independent integrals  
=  
# bounded regions.

# Differential Equations

Consequently, there exists a **differential equation** of the form:

$$d\vec{I} = \varepsilon A \vec{I}$$

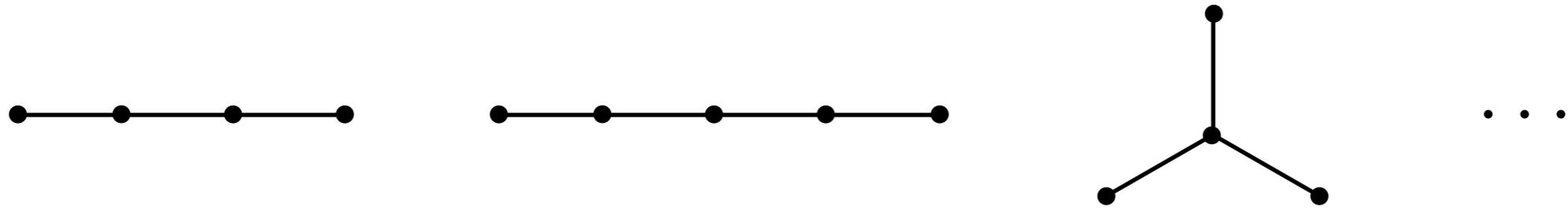
$$A = \begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 \end{bmatrix} d \log(X_1 + X_2) + \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix} d \log(X_1 + Y) + \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} d \log(X_2 + Y) \\ + \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} d \log(X_1 - Y) + \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} d \log(X_2 - Y)$$

↑  
singularities (letters)

# More Complicated Graphs

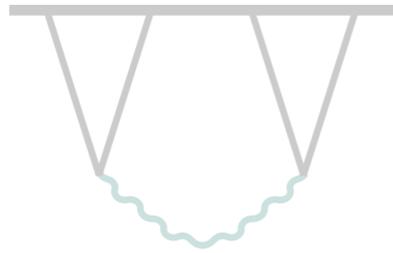
One can proceed algorithmically and derive equations for arbitrary graphs.

However, the underlying physics becomes quite obscure.

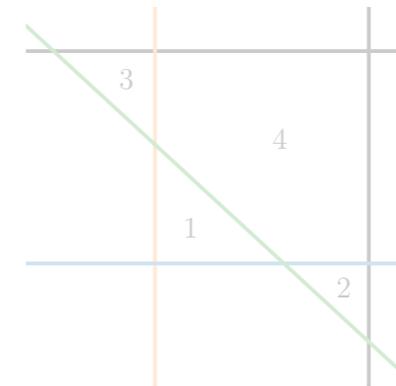


It turns out to be much more useful to represent equations **graphically**.

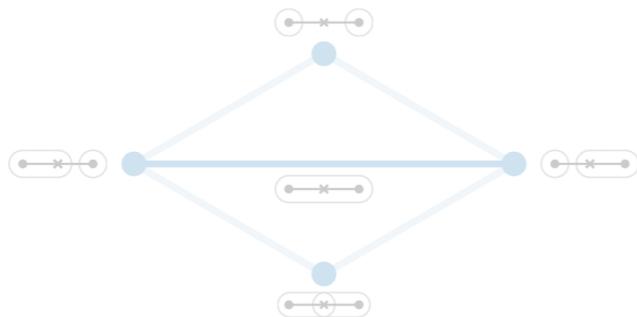
## 1. Correlators in dS



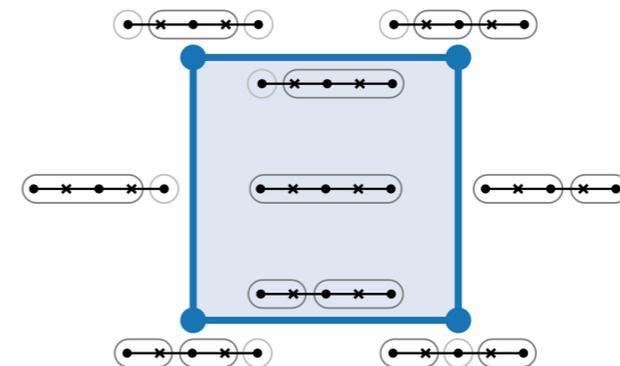
## 2. Correlators in Toy Universe



## 4. A Hidden Pattern in dS



## 3. A Hidden Pattern in Toy Universe

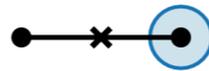


# Letters

The **singularities (letters)** of the equations can be represented as



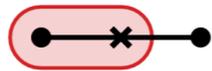
$$d \log(X_1 + Y)$$



$$d \log(X_2 + Y)$$



$$d \log(X_1 + X_2)$$



$$d \log(X_1 - Y)$$



$$d \log(X_2 - Y)$$

with connected tubings of a graph.

# Functions

Similarly, the **basis functions** can be represented as

$$\vec{I} = \left( \begin{array}{c} \text{---} \circ \text{---} \times \text{---} \circ \text{---} \\ I_1 \end{array}, \begin{array}{c} \text{---} \circ \text{---} \text{---} \times \text{---} \text{---} \circ \text{---} \\ I_2 \end{array}, \begin{array}{c} \text{---} \text{---} \times \text{---} \text{---} \circ \text{---} \\ I_3 \end{array}, \begin{array}{c} \text{---} \text{---} \text{---} \times \text{---} \text{---} \circ \text{---} \\ I_4 \end{array} \right)$$

with complete (possibly disconnected) tubings of a graph.

# Differential Equations

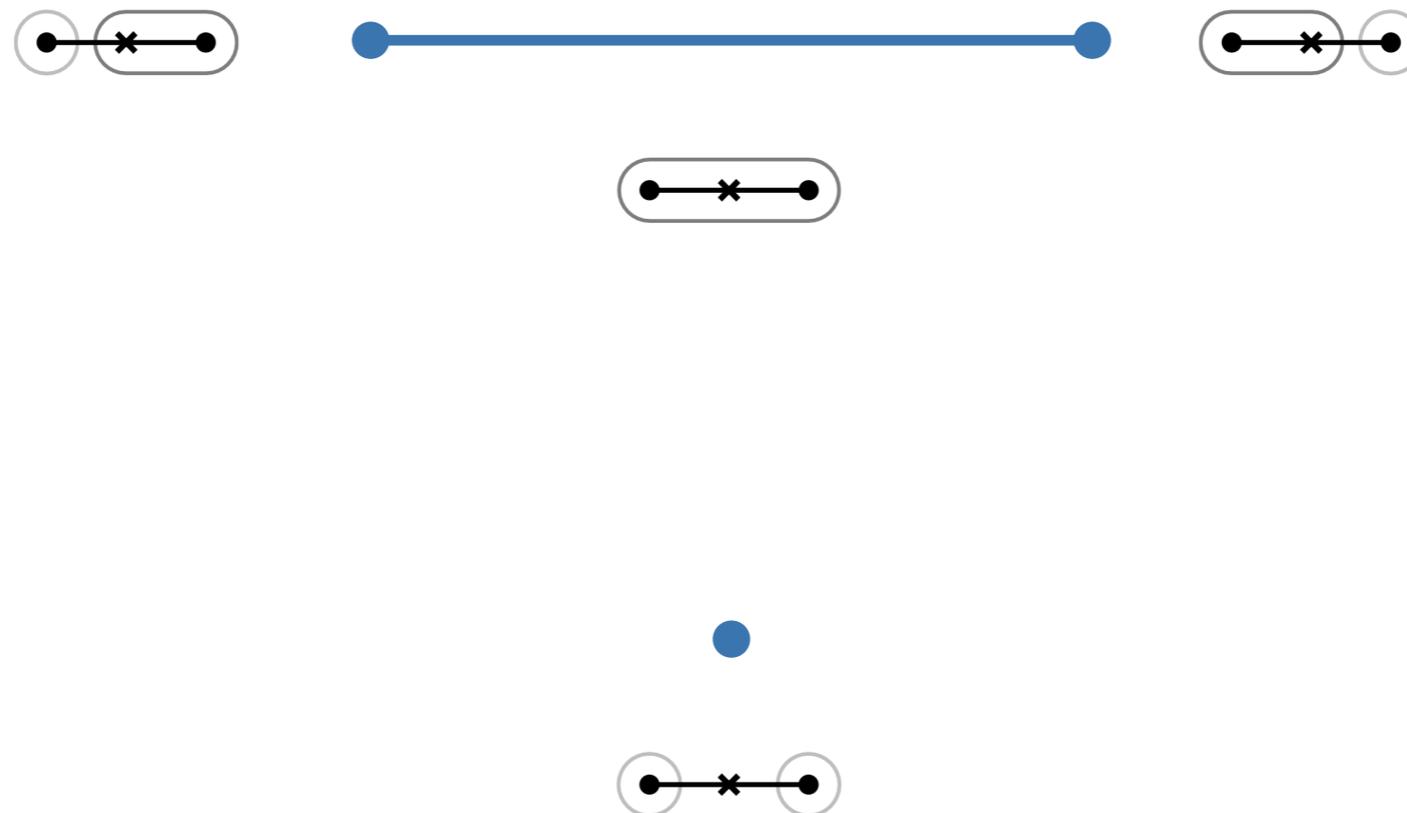
In terms of pictures, the differential equations take the form

$$\begin{aligned}
 d \begin{array}{c} \circ \text{---} * \text{---} \circ \end{array} &= \begin{array}{c} \color{red}{\circ} \text{---} * \text{---} \bullet \end{array} \begin{array}{c} \circ \text{---} * \text{---} \circ \end{array} + \begin{array}{c} \bullet \text{---} * \text{---} \color{blue}{\circ} \end{array} \begin{array}{c} \circ \text{---} * \text{---} \circ \end{array} \\
 d \begin{array}{c} \circ \text{---} * \text{---} \bullet \end{array} &= \begin{array}{c} \color{red}{\circ} \text{---} * \text{---} \bullet \end{array} \left( \begin{array}{c} \circ \text{---} * \text{---} \bullet \end{array} - \begin{array}{c} \bullet \text{---} * \text{---} \bullet \end{array} \right) + \begin{array}{c} \bullet \text{---} * \text{---} \color{blue}{\circ} \end{array} \left( \begin{array}{c} \circ \text{---} * \text{---} \bullet \end{array} + \begin{array}{c} \bullet \text{---} * \text{---} \bullet \end{array} \right) \\
 d \begin{array}{c} \bullet \text{---} * \text{---} \circ \end{array} &= \begin{array}{c} \bullet \text{---} * \text{---} \color{blue}{\circ} \end{array} \left( \begin{array}{c} \bullet \text{---} * \text{---} \circ \end{array} - \begin{array}{c} \bullet \text{---} * \text{---} \bullet \end{array} \right) + \begin{array}{c} \color{red}{\bullet} \text{---} * \text{---} \circ \end{array} \left( \begin{array}{c} \bullet \text{---} * \text{---} \circ \end{array} + \begin{array}{c} \bullet \text{---} * \text{---} \bullet \end{array} \right) \\
 d \begin{array}{c} \bullet \text{---} * \text{---} \bullet \end{array} &= 2 \begin{array}{c} \bullet \text{---} * \text{---} \bullet \end{array} \begin{array}{c} \bullet \text{---} * \text{---} \bullet \end{array}
 \end{aligned}$$

Remarkably, there exists an underlying **geometry** that explains this pattern.

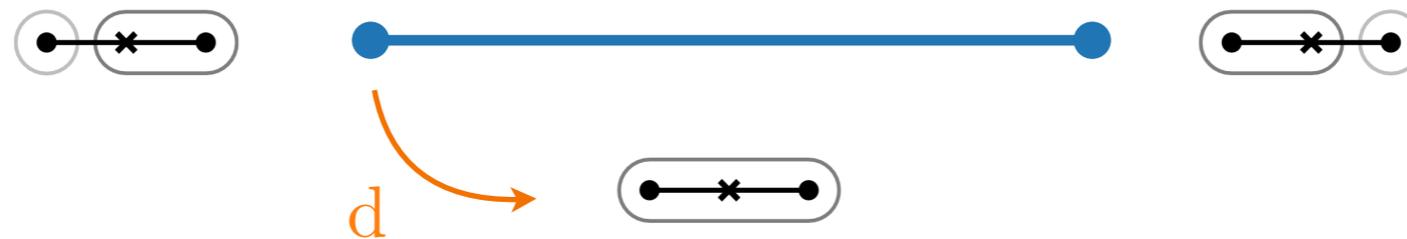
# Geometric Arrangement

The basis functions can be arranged geometrically as



# Kinematic Flow

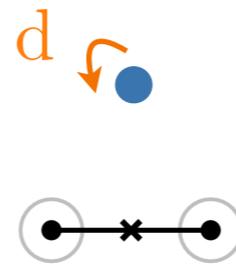
The differential then becomes **local** in this geometric space of functions.



$$\begin{aligned}
 d \left( \text{circle} \text{---} \text{oval} \right) &= \text{red circle} \text{---} \text{oval} \left( \text{circle} \text{---} \text{oval} - \text{oval} \right) \\
 &+ \text{oval} \text{---} \text{blue oval} \left( \text{circle} \text{---} \text{oval} + \text{oval} \right)
 \end{aligned}$$

# Kinematic Flow

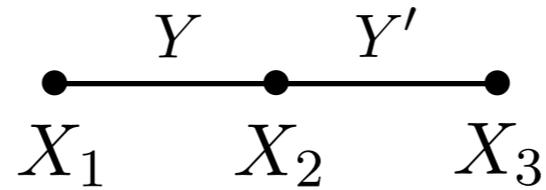
The differential then becomes **local** in this geometric space of functions.



$$d \left( \text{node} \times \text{node} \right) = \left( \text{red node} \times \text{node} \right) + \left( \text{node} \times \text{blue node} \right) + \left( \text{node} \times \text{node} \right)$$

A diagram illustrating the differential operator  $d$  acting on a product of two nodes. The equation is enclosed in a dashed rectangular box. On the left, the operator  $d$  is applied to a product of two nodes (black dots in white circles) connected by a horizontal line with an 'x' mark. This is equal to the sum of three terms: 1) a node with a red highlight multiplied by a node, 2) a node multiplied by a node with a blue highlight, and 3) a node multiplied by a node. Each term in the sum is represented by a horizontal line with an 'x' mark connecting the nodes.

# More Complicated Graphs



**Letters:** connected tubings of a marked graph.

$$\text{---} \circ \text{---} \times \text{---} \times \text{---} \bullet \equiv d \log(X_1 + Y),$$

$$\text{---} \times \text{---} \times \text{---} \times \text{---} \bullet \equiv d \log(X_3 + Y'),$$

$$\text{---} \times \text{---} \circ \text{---} \times \text{---} \bullet \equiv d \log(X_2 + Y + Y'),$$

$$\text{---} \times \text{---} \bullet \text{---} \times \text{---} \bullet \equiv d \log(X_1 + X_2 + Y'),$$

$$\text{---} \times \text{---} \bullet \text{---} \times \text{---} \bullet \equiv d \log(X_2 + X_3 + Y),$$

$$\text{---} \times \text{---} \bullet \text{---} \times \text{---} \bullet \equiv d \log(X_1 + X_2 + X_3).$$

$$\text{---} \bullet \text{---} \times \text{---} \times \text{---} \bullet \equiv d \log(X_1 - Y),$$

$$\text{---} \times \text{---} \bullet \text{---} \times \text{---} \bullet \equiv d \log(X_3 - Y'),$$

$$\text{---} \bullet \text{---} \times \text{---} \times \text{---} \bullet \equiv d \log(X_2 - Y + Y'),$$

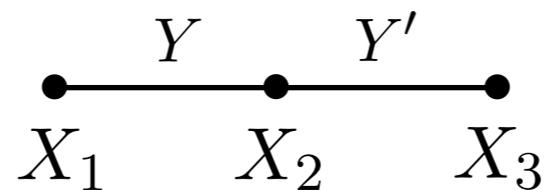
$$\text{---} \bullet \text{---} \times \text{---} \times \text{---} \bullet \equiv d \log(X_2 - Y - Y'),$$

$$\text{---} \times \text{---} \bullet \text{---} \times \text{---} \bullet \equiv d \log(X_2 + Y - Y'),$$

$$\text{---} \bullet \text{---} \times \text{---} \times \text{---} \bullet \equiv d \log(X_1 + X_2 - Y'),$$

$$\text{---} \bullet \text{---} \times \text{---} \times \text{---} \bullet \equiv d \log(X_2 + X_3 - Y'),$$

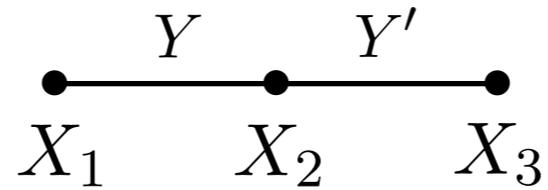
# More Complicated Graphs



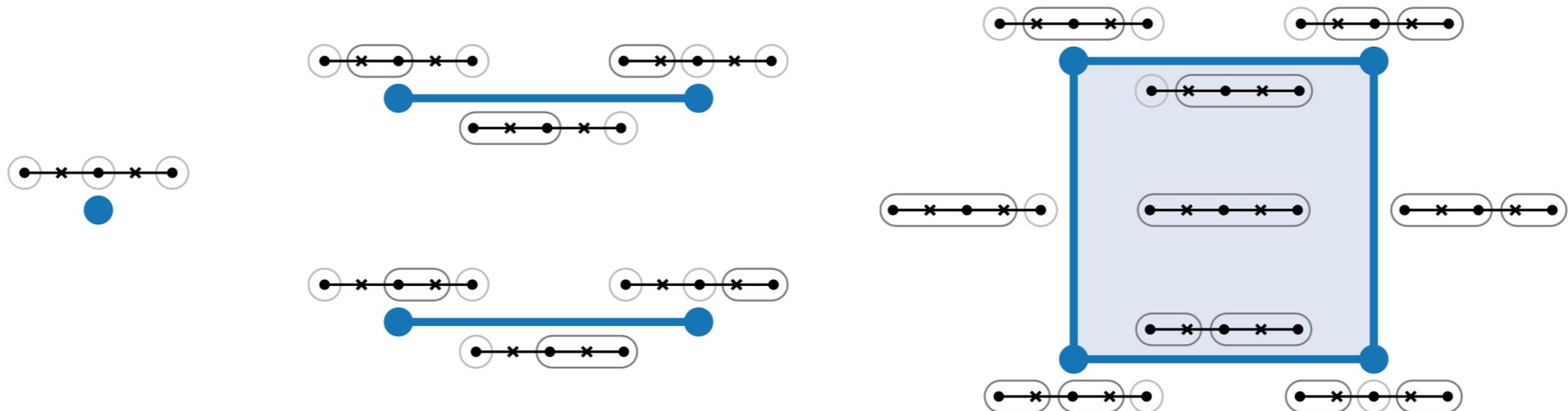
**Functions:** complete tubings of a marked graph.



# More Complicated Graphs

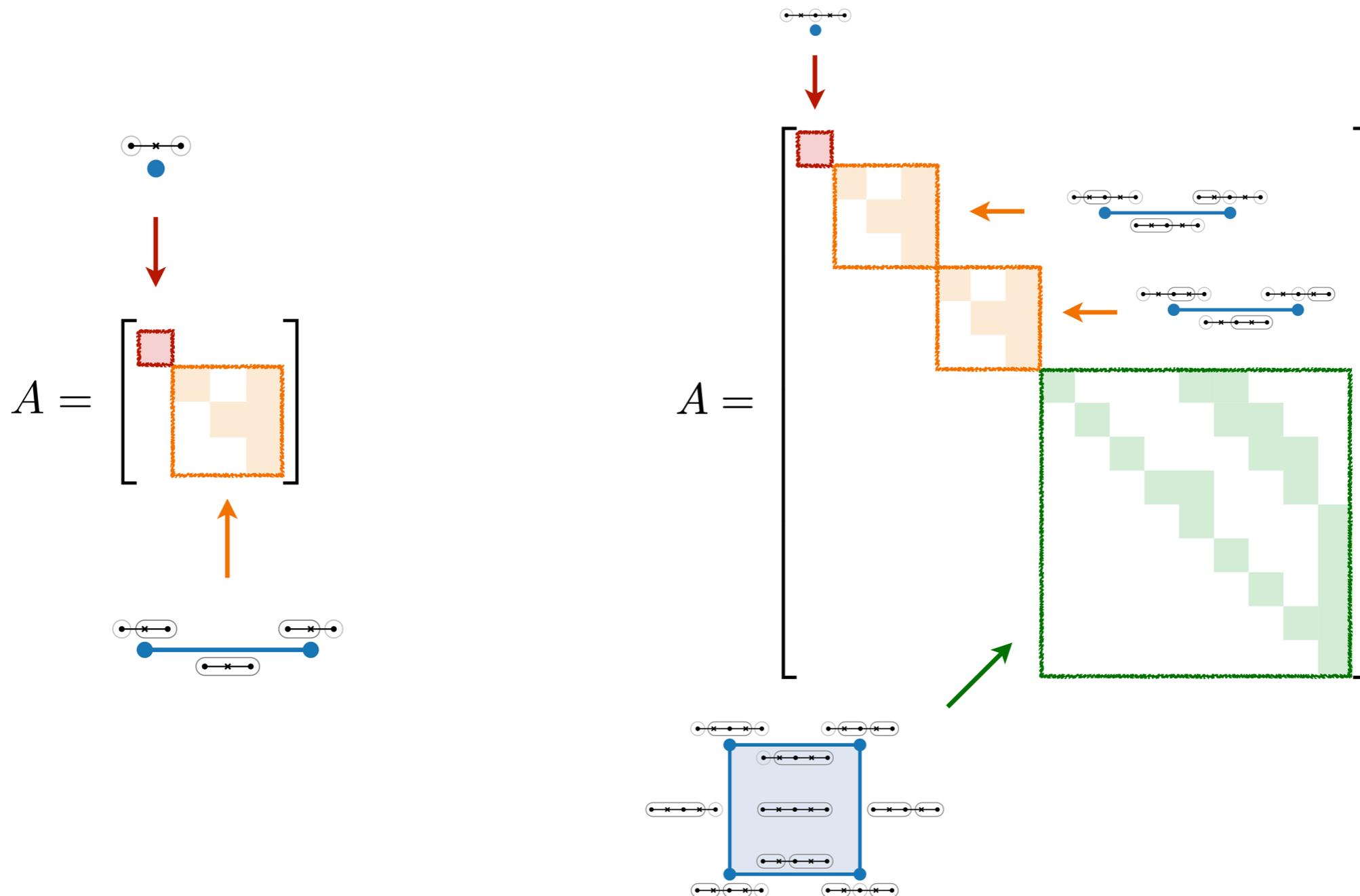


**Functions:** can be arranged into a point, two intervals, and a square.



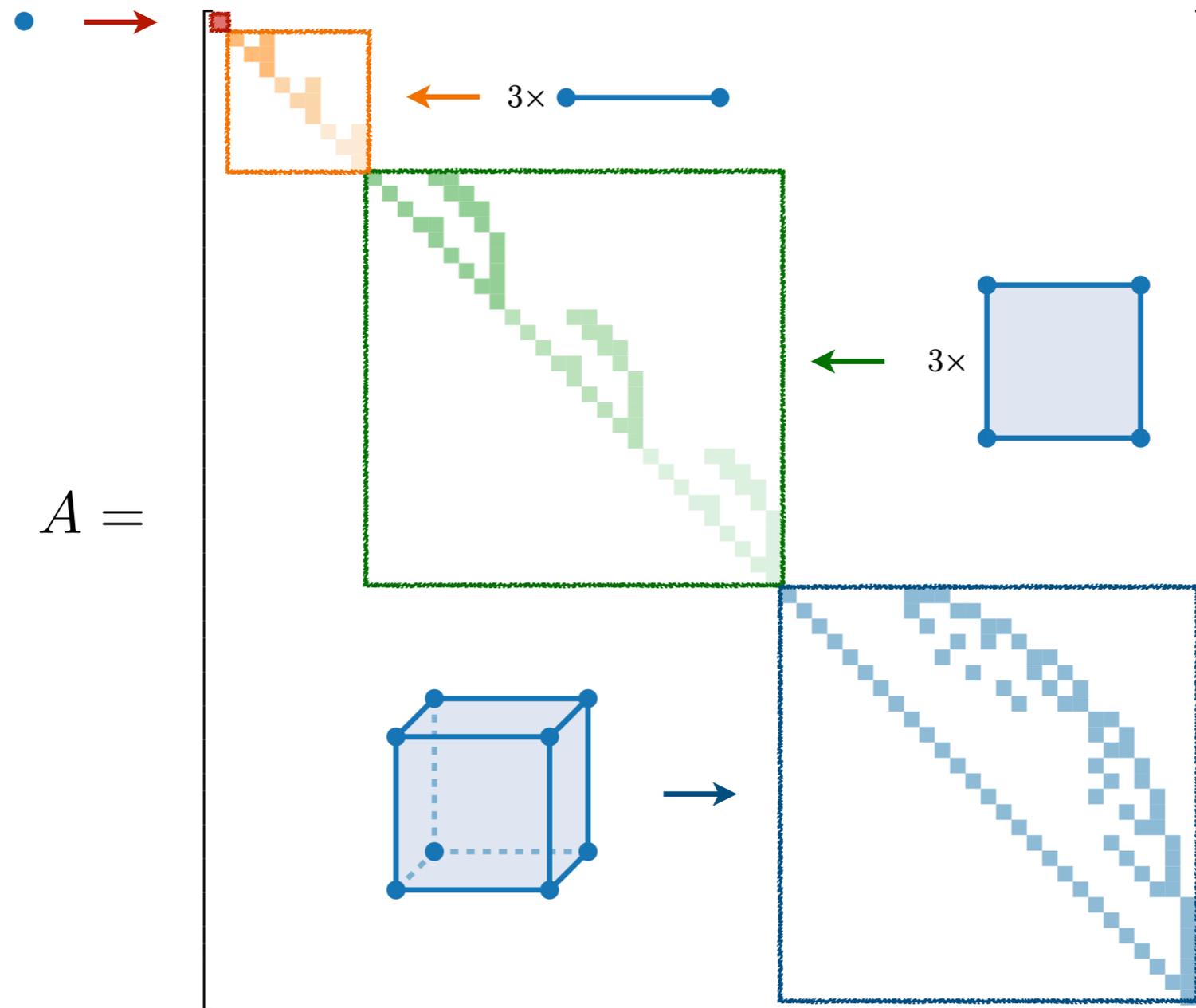
# Differential Equations

All differential equations can be easily derived using the kinematic flow rules.



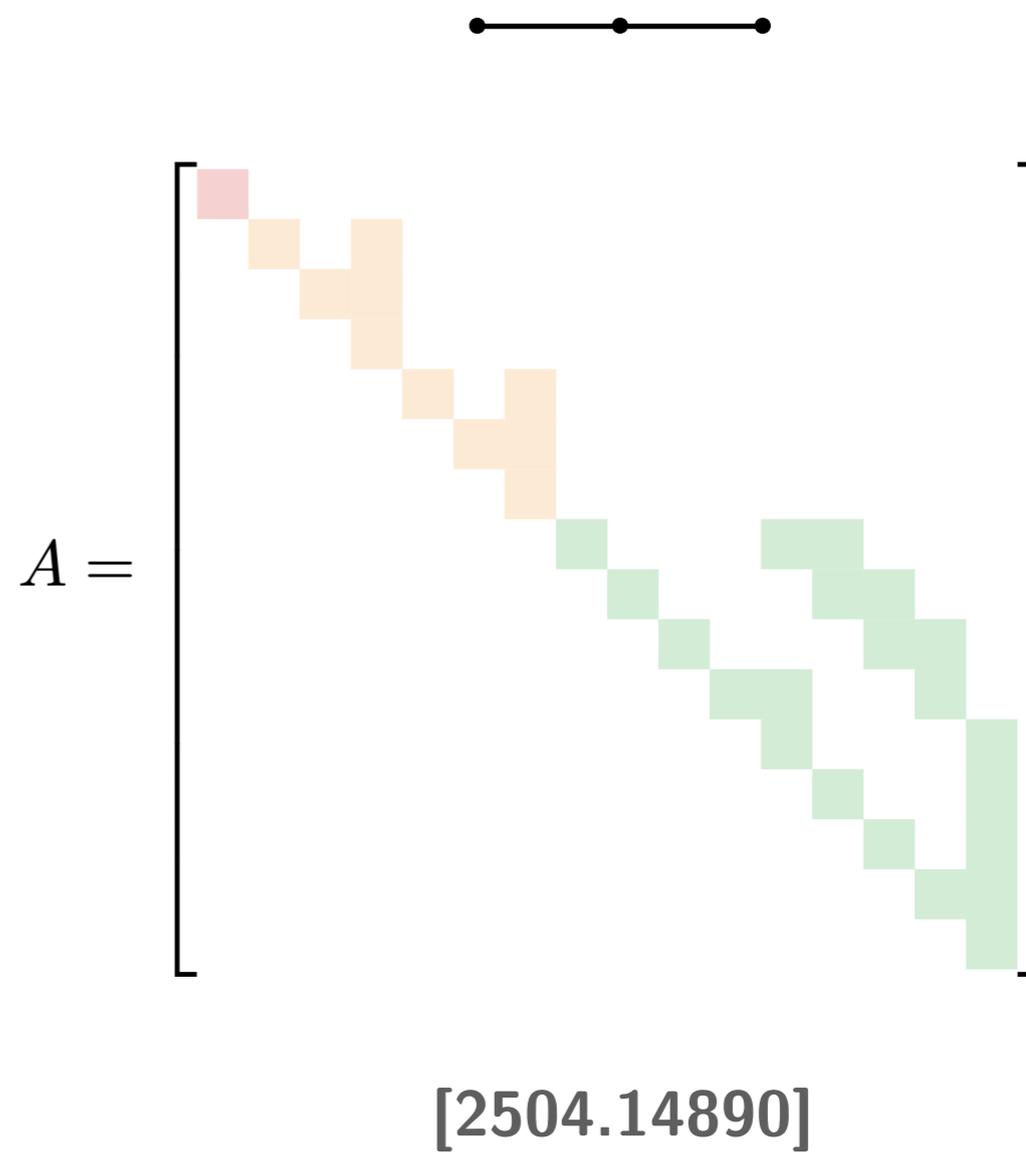
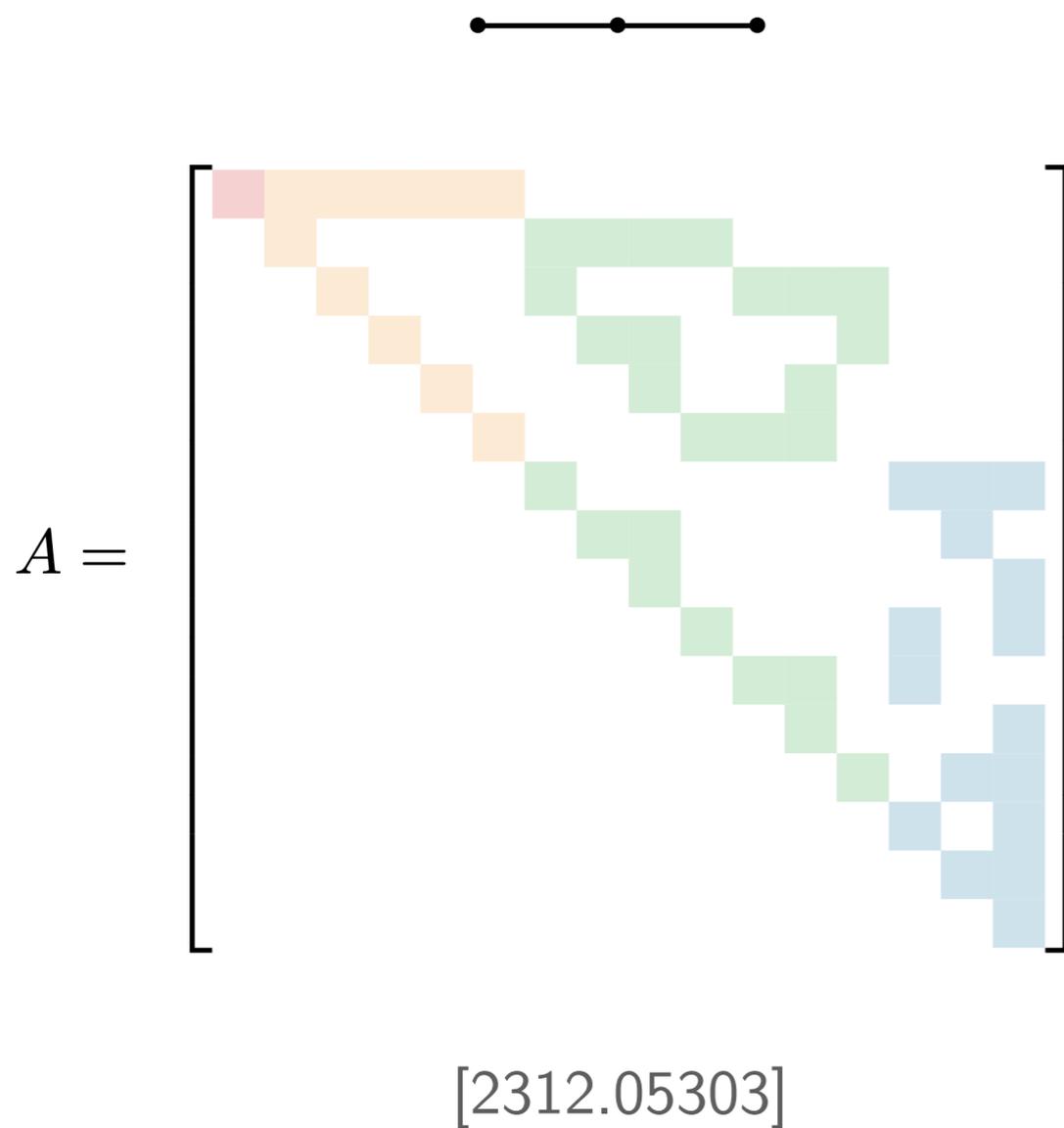
# Differential Equations

All differential equations can be easily derived using the kinematic flow rules.



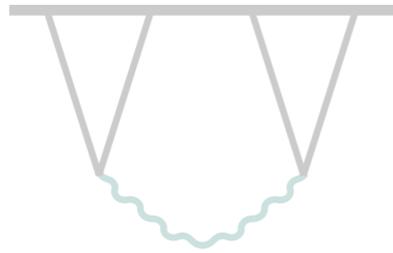
# Differential Equations

This geometric organization of tubings dramatically simplifies the equations.

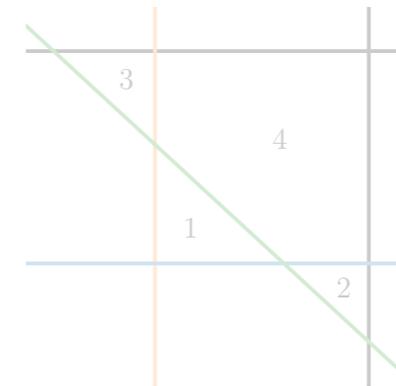


[See also H. Goodhew's talk]

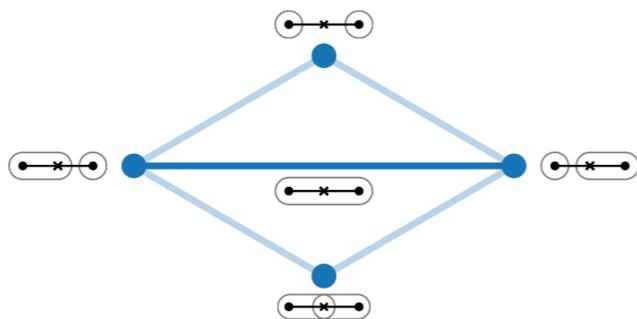
## 1. Correlators in dS



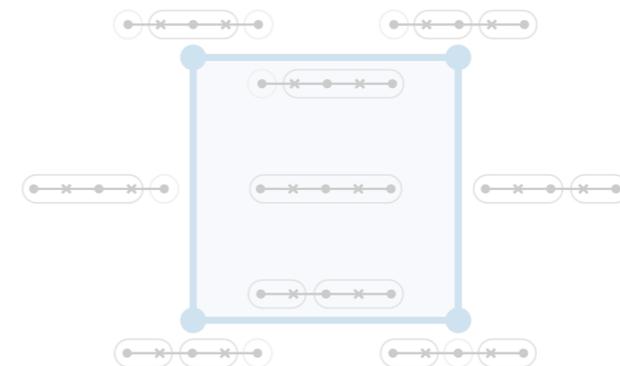
## 2. Correlators in Toy Universe



## 4. A Hidden Pattern in dS



## 3. A Hidden Pattern in Toy Universe

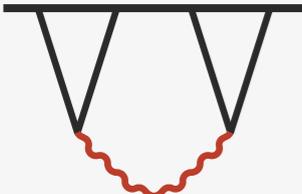


# Beyond Toy Model

Processes involving **massive particles in dS** can be understood in a similar way.

mass parameter  
(deviation from cc scalar)

↓



$$\supset \int_0^\infty \frac{dx_1 dx_2}{(x_1 x_2)^{1+\alpha}} \int_1^\infty ds_1 ds_2 \frac{x_1^{-\xi} x_2^{-\xi} (s_1^2 - 1)^\xi (s_2^2 - 1)^\xi}{(x_1 + x_2 + X_1 + X_2 + Y(s_1 - s_2))(x_2 + X_2 + Y)}$$

↗  $d$ -dependent parameter

↖ two extra integrals

This leads to a larger integral basis, but similar structures remain.

# Massive DEQ

The resulting DEQ has the following schematic structure:

$$A = \alpha \left[ \begin{array}{c} \text{---} \\ \begin{array}{c} \text{orange} \\ \text{orange} \\ \text{red} \\ \text{red} \\ \text{blue} \end{array} \end{array} \right] + \xi \left[ \begin{array}{c} \text{---} \\ \begin{array}{c} \text{red} \\ \text{orange} \end{array} \end{array} \right]$$

conformally coupled scalar in dS

mass dependence in dS (exact in  $\xi$ )

This can be solved in the small (near cc) or large (heavy mass)  $\xi$  limits.

# Massive Kinematic Flow

We found an analogous kinematic flow pattern that controls these new DEQ.

$$d\psi_{\text{---}\ast\text{---}} = \left( \alpha_1 \text{---}\ast\text{---} + \alpha_2 \text{---}\ast\text{---}\text{---}\text{---} \right) \psi_{\text{---}\ast\text{---}} + \left( \text{---}\ast\text{---} - \text{---}\ast\text{---}\text{---}\text{---} \right) F_{\text{---}\ast\text{---}}$$

$$+ \xi \left[ \left( \text{---}\ast\text{---} - \text{---}\ast\text{---} \right) \psi_{\text{---}\ast\text{---}} + \left( \text{---}\ast\text{---}\text{---}\text{---} - \text{---}\ast\text{---} \right) \psi_{\text{---}\ast\text{---}} \right].$$

$$d\psi_{\text{---}\ast\text{---}} = \left( \alpha_1 \text{---}\ast\text{---} + \alpha_2 \text{---}\ast\text{---}\text{---}\text{---} \right) \psi_{\text{---}\ast\text{---}}$$

$$+ \xi \left[ \left( \text{---}\ast\text{---} - \text{---}\ast\text{---} \right) \psi_{\text{---}\ast\text{---}} + \left( \text{---}\ast\text{---}\text{---}\text{---} - \text{---}\ast\text{---} \right) \psi_{\text{---}\ast\text{---}} \right],$$

new function

$$d\psi_{\text{---}\ast\text{---}} = \left( \alpha_1 \text{---}\ast\text{---} + \alpha_2 \text{---}\ast\text{---}\text{---}\text{---} \right) \psi_{\text{---}\ast\text{---}}$$

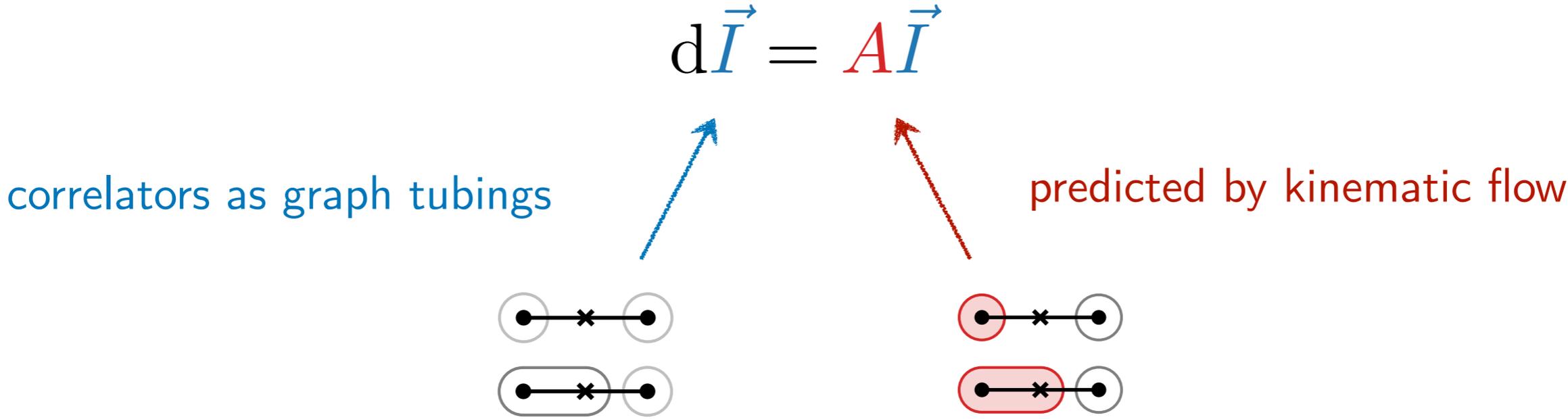
$$+ \xi \left[ \left( \text{---}\ast\text{---} - \text{---}\ast\text{---} \right) \psi_{\text{---}\ast\text{---}} + \left( \text{---}\ast\text{---}\text{---}\text{---} - \text{---}\ast\text{---} \right) \psi_{\text{---}\ast\text{---}} \right],$$

$$dF_{\text{---}\ast\text{---}} = (\alpha_1 + \alpha_2) \text{---}\ast\text{---} F_{\text{---}\ast\text{---}}.$$

# Conclusion

# Conclusion

We have started to uncover a **combinatorial and geometric** pattern underlying the differential equations for cosmological correlators.



**Simple graphical rules** allow us to easily derive the differential equations.

# Open Problems

There are many outstanding questions:

- ▶ Why does this work?
- ▶ What is the geometric origin of the massive kinematic flow?
- ▶ How general is this structure?
- ▶ Does it generalize to loop amplitudes and holographic correlators?